### Robust Image Denoising of No-Flash Images Guided by Consistent Flash Images

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# OUTLINE

- Authorship
- Background
- Method
- Experiments
- Conclusion

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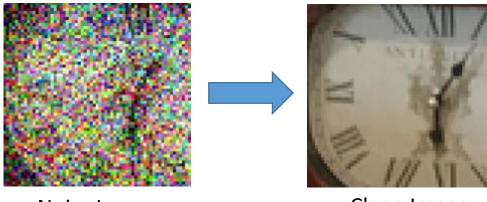
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### BACKGROUND: KPN

#### Image Denoising

- Recover clean images from noisy input images
- Noise Model:  $I_i^N = I_i + \epsilon_i \quad \epsilon_i \sim \mathcal{N}(I_i, \sigma_r^2 + \sigma_s I_i)$
- Estimate:

$$\hat{I}_{c} = \frac{1}{\sum_{i \in \Omega_{c}} w_{ci}} \sum_{i \in \Omega_{c}} w_{ci} \left\{ I_{i}^{N} \right\}$$



Noisy Image

Clean Image

### BACKGROUND

#### Image Denoising

- Bottleneck:
  - Loss of high-frequency details
  - Blending colors across edges
  - Over-smooth



Noisy Image



Ground Truth



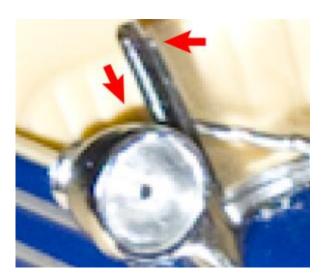
Denoise Result

### BACKGROUND

#### Image Denoising Guided by Flash

- Contain high-frequency details
- Serve as edge-stopping functions
- Bottleneck: Additional image structures





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### **METHOD:** Deep Combiner

• For Noisy Image:

$$I_i^N = I_i + \epsilon_i$$

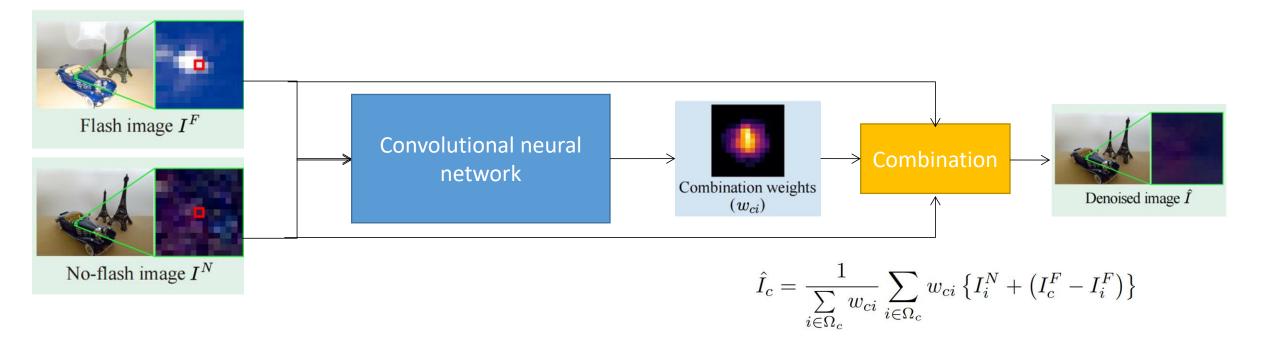
• For Flash/No-flash Pairs:

$$I_c^F - I_i^F = I_c - I_i + \epsilon_{ci}$$

• To estimate the c-th pixel  $\hat{I_c}$ 

$$J_{c} = \frac{1}{2} w_{cc} \left( I_{c}^{N} - \hat{I}_{c} \right)^{2} + \sum_{i \in \Omega_{c}, i \neq c} w_{ci} \left( I_{i}^{N} - \hat{I}_{i} \right)^{2} + \sum_{i \in \Omega_{c}, i \neq c} w_{ci} \left\{ \left( I_{c}^{F} - I_{i}^{F} \right) - \left( \hat{I}_{c} - \hat{I}_{i} \right) \right\}^{2},$$
$$\hat{I}_{c} = \frac{1}{\sum_{i \in \Omega_{c}} w_{ci}} \sum_{i \in \Omega_{c}} w_{ci} \left\{ I_{i}^{N} + \left( I_{c}^{F} - I_{i}^{F} \right) \right\}$$

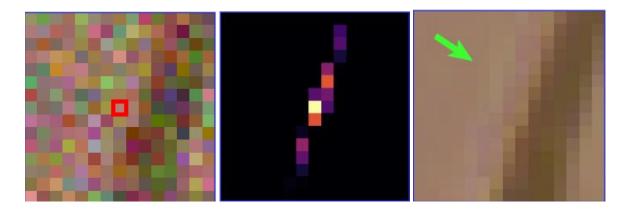
### **METHOD: Deep Combiner**



#### Drawbacks



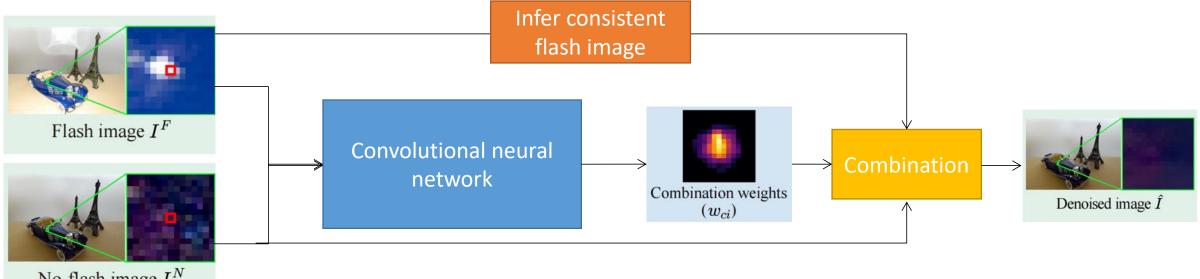
$$I_c^F - I_i^F = I_c - I_i + \epsilon_{ci}$$



Noisy Image Combination Weights Result

Ground Truth/Flash Image

#### Improvement



No-flash image  $I^N$ 

• Deep Combiner:

$$I_c^F - I_i^F = I_c - I_i + \epsilon_{ci}$$

• RIDFnF:

$$\left(k_c * I^F\right)_c - \left(k_c * I^F\right)_i = I_c - I_i + \epsilon_{ci}$$

• To estimate the c-th pixel  $\hat{I}_c$ 

$$J_{c} = \frac{1}{2} w_{cc} \left( I_{c}^{N} - \hat{I}_{c} \right)^{2} + \sum_{i \in \Omega_{c}, i \neq c} w_{ci} \left( I_{i}^{N} - \hat{I}_{i} \right)^{2}$$

$$+ \sum_{i \in \Omega_{c}, i \neq c} w_{ci} \Big[ \Big\{ \Big( k_{c} * I^{F} \Big)_{c} - \Big( k_{c} * I^{F} \Big)_{i} \Big\} - \Big( \hat{I}_{c} - \hat{I}_{i} \Big) \Big]^{2}$$

• minimized by setting its gradients with respect to  $\hat{I}_c$  and  $\hat{I}_i$  zero

$$\begin{aligned} \frac{\partial J_c}{\partial \hat{I}_c} &= w_{cc} \left( I_c^N - \hat{I}_c \right) \\ &+ 2 \sum_{i \in \Omega_c, i \neq c} w_{ci} \left[ \left\{ \left( k_c * I^F \right)_c - \left( k_c * I^F \right)_i \right\} - \left( \hat{I}_c - \hat{I}_i \right) \right] \\ &= 0, \end{aligned} \qquad \begin{aligned} &= 0. \end{aligned} \qquad \begin{aligned} \frac{\partial J_c}{\partial \hat{I}_i} &= -w_{ci} \left( I_i^N - \hat{I}_i \right) \\ &+ w_{ci} \left[ \left\{ \left( k_c * I^F \right)_c - \left( k_c * I^F \right)_i \right\} - \left( \hat{I}_c - \hat{I}_i \right) \right] \\ &= 0. \end{aligned}$$

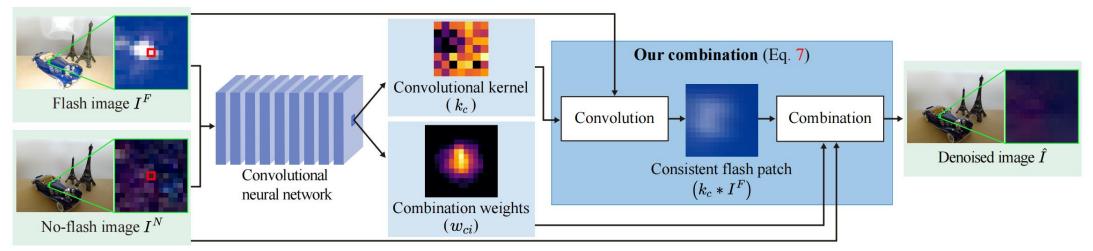
• Setting  $\frac{\partial J_c}{\partial \hat{I}_i} = 0$ :

$$\hat{I}_{i} = \frac{1}{2} \left\{ I_{i}^{N} - \left( k_{c} * I^{F} \right)_{c} + \left( k_{c} * I^{F} \right)_{i} + \hat{I}_{c} \right\}$$

• Plug this equation into  $\frac{\partial J_c}{\partial \hat{I}_c}$ 

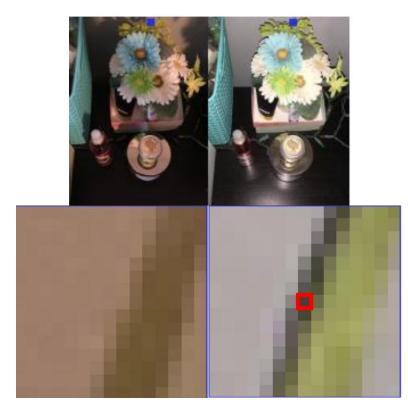
$$\hat{I}_{c} = \frac{1}{\sum_{i \in \Omega_{c}} w_{ci}} \sum_{i \in \Omega_{c}} w_{ci} \{ I_{i}^{N} + (k_{c} * I^{F})_{c} - (k_{c} * I^{F})_{i} \}$$

#### **Network Architecture**

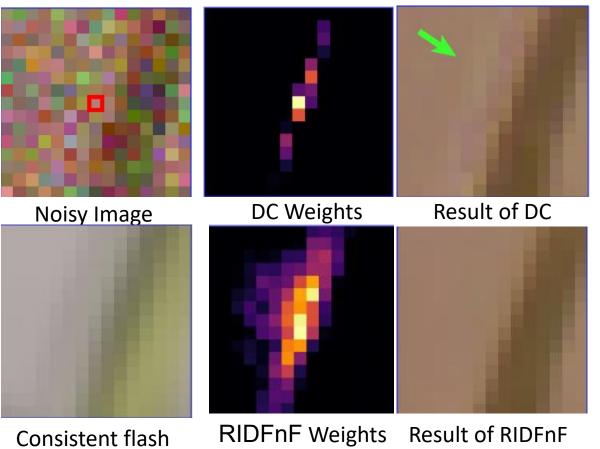


#### **Network Details**

- k<sub>c</sub> a normalized kernel whose elements are non-negative
- $k_c$  size: (7×7)  $\Omega_c$  size: (15×15)
- Training loss: L2 Loss
- Trainable parameters: 1.84M



Ground Truth/Flash Image



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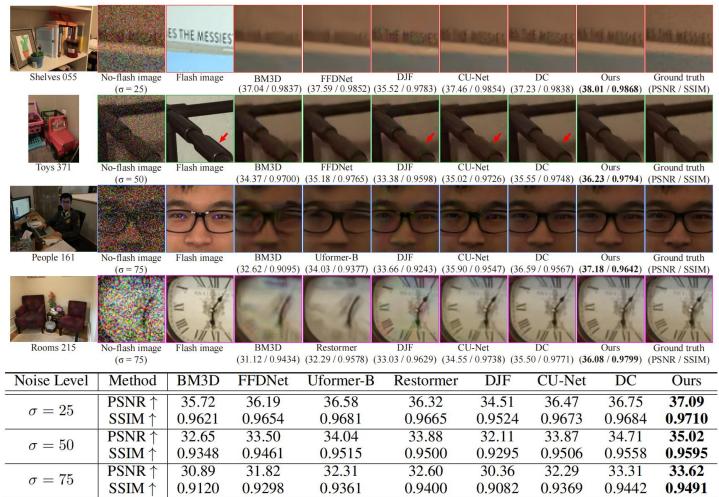
#### Datasets: Flash and Ambient Illuminations Dataset(FAID)

- Includes 2775 flash/no-flash image pairs categorized into six classes
- 2263 for training, 256 for validation, 256 for testing

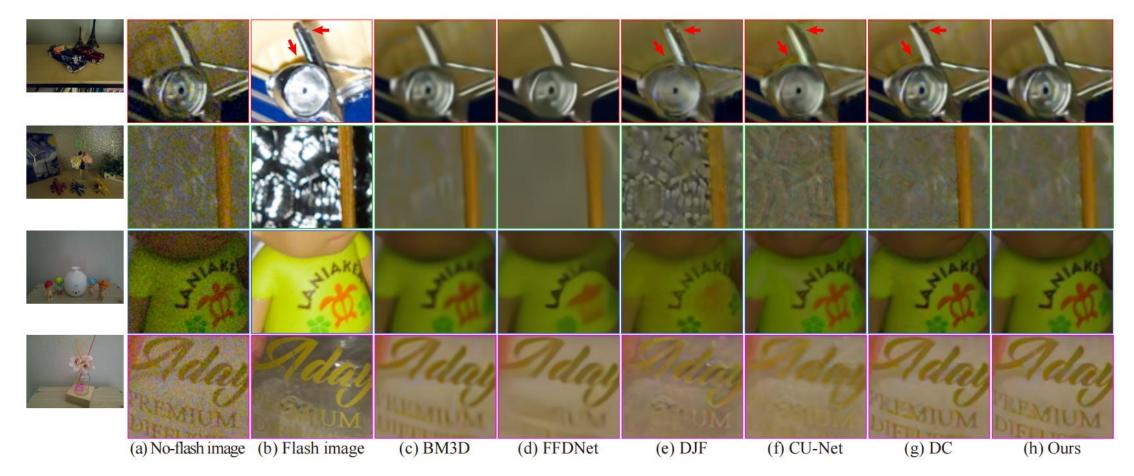
#### **Training Details**

- Training for 50 epochs
- Learning rate:  $5e-4 \rightarrow 1e-4$
- Image patches: (64×64)
- Batch size: 64

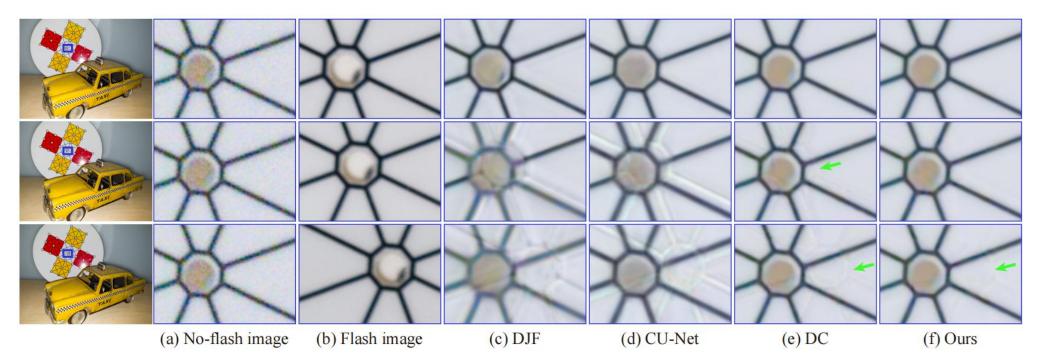
#### Comparisons using Gaussian noise



#### Comparisons using Real Noise



Analysis using misaligned flash/no-flash pairs



#### Ablation studies

- Different consistent flash generations
  - Gaussian

Produce the band-width of a Gaussian filter per pixel

• Direct

Produces consistent flash images

Methods	DC PSNR↑	Gaussian PSNR ↑	Direct PSNR ↑	Convolutional $k_c$ PSNR $\uparrow$
$\sigma = 25$	36.75	36.98	37.02	37.09
$\sigma = 50$	34.71	34.92	34.89	35.02
$\sigma = 75$	33.31	33.54	33.45	33.62

Analysis of convolutional kernel sizes

• Varying the kernel size K  $\times$ K from 1 $\times$ 1 to 9 $\times$ 9

Kernel size	$1 \times 1$	$3 \times 3$	$5 \times 5$	$7 \times 7$	$9 \times 9$
Kerner size	PSNR ↑	PSNR ↑	PSNR ↑	PSNR ↑	$PSNR \uparrow$
$\sigma = 25$	36.75	37.02	37.07	37.09	37.10
$\sigma = 50$	34.69	34.97	35.00	35.02	35.02
$\sigma = 75$	33.29	33.58	33.61	33.62	33.61
Inference time	0.76 s	0.78 s	1.12 s	1.70 s	2.66 s

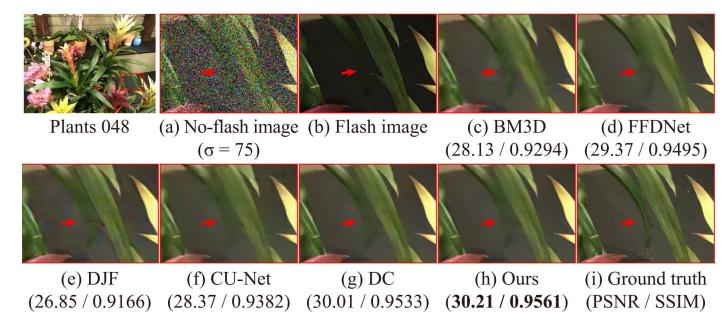
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### CONCLUSION

Discussion of limitations and future work

- The benefit disappear when flash image doesn't capture high-frequency details
- Do not explicitly model a misalignment



## CONCLUSION

- Infer a consistent image patch, which is structurally similar to the ground truth, by applying per-pixel convolutional kernels to an input flash image locally.
- We combine a noisy no-flash image and inferred consistent image locally via a new combination model and output a denoised no-flash image.

# Thanks for listening!