### Minimalist Vision with Freeform Pixels

Jeremy Klotz and Shree K. Nayar

Columbia University

ECCV 2024 Best Paper

PRESENTER: LILANG LIN

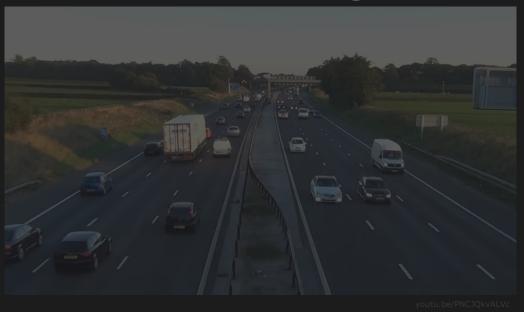
2024/10/13

## Lightweight Vision

#### Workspace Monitoring



**Traffic Monitoring** 



How many people are in the room?

How fast is traffic moving?

Which desks are occupied High-Level Inference is there an accident?

Statistics of Objects

Aggregate Motion of Objects

## Lightweight Vision

Scene



Camera

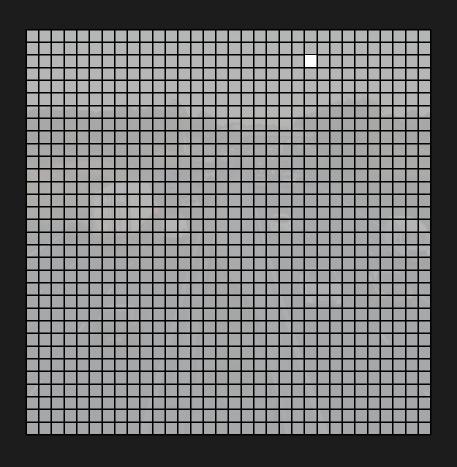
Capt@actumedslidements

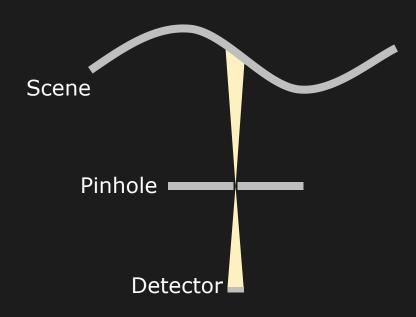


#### Benefits

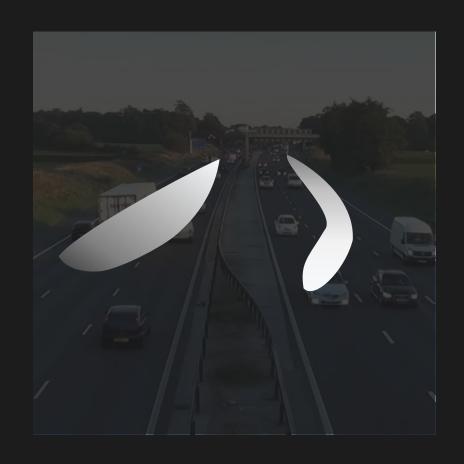
Privacy Preservation Self-Sustainability

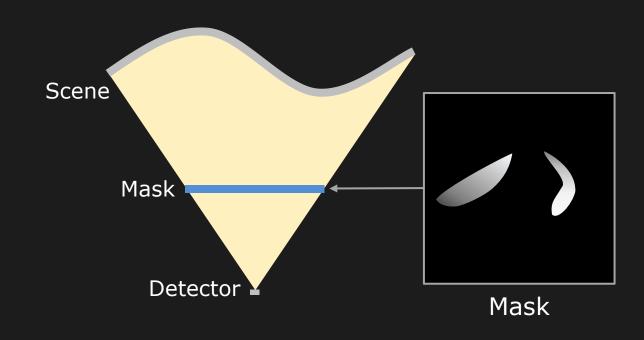
## **Square Pixels**



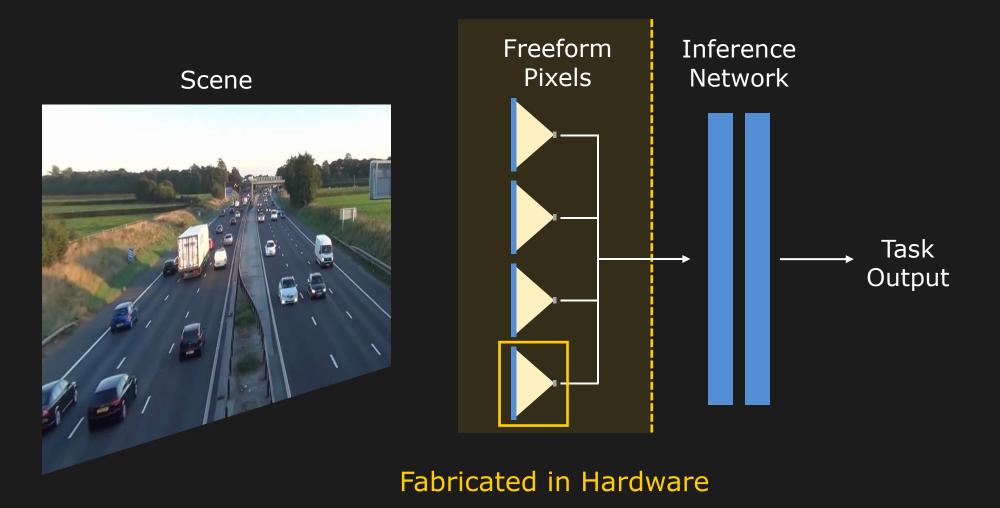


## Freeform Pixels

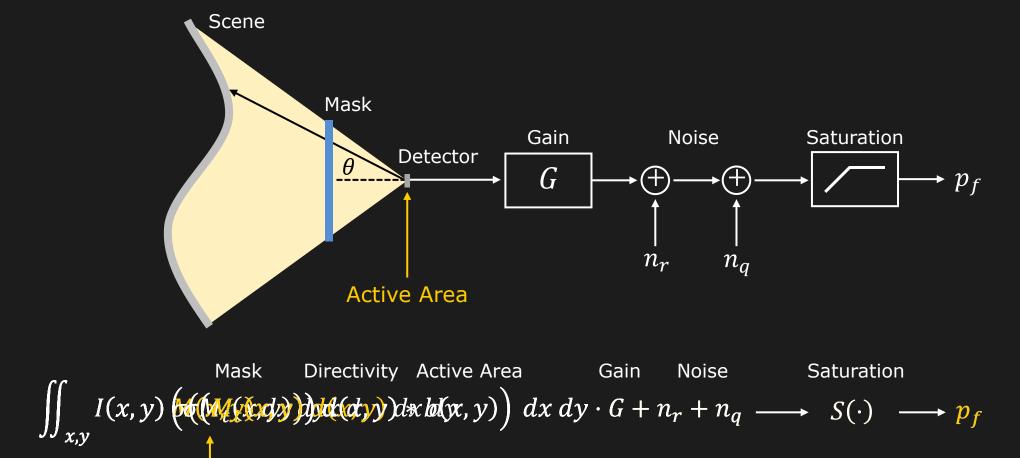




## Minimalist Vision



### Sensor Model



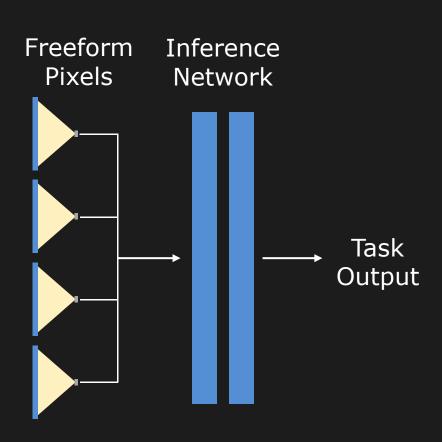
Transmittance in [0, 1]

Measurement is Differentiable w.r.t. Mask Parameters

## Minimalist Vision with Sensor Model

#### Scene

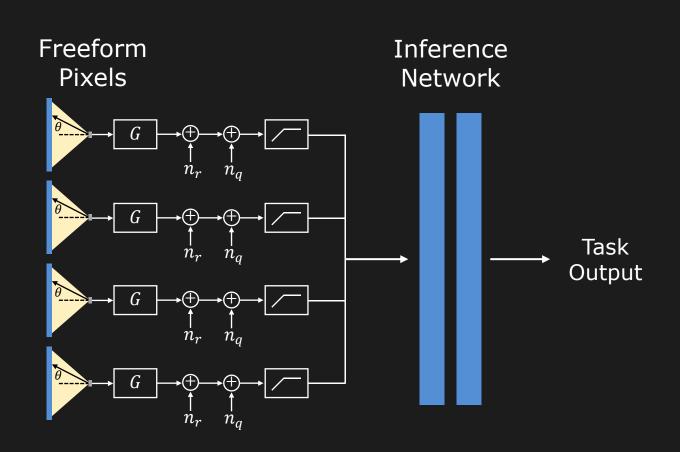




## Minimalist Vision with Sensor Model

#### Scene

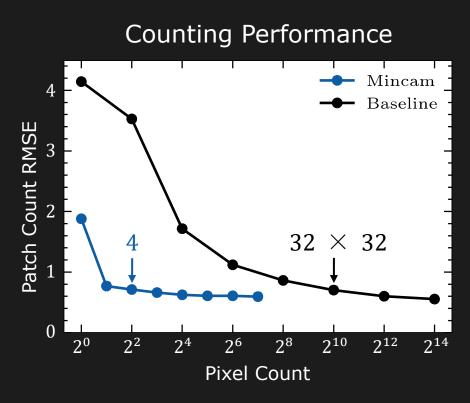




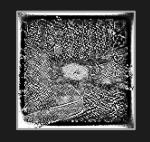
## Toy Problem

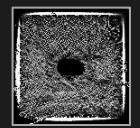
Counting Patches

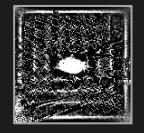


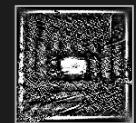


Freeform Pixels



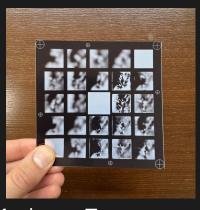






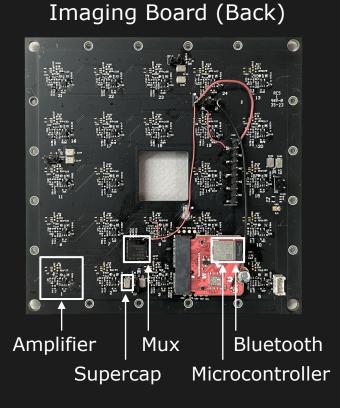
## Minimalist Camera Prototype





Imaging Board (Front)

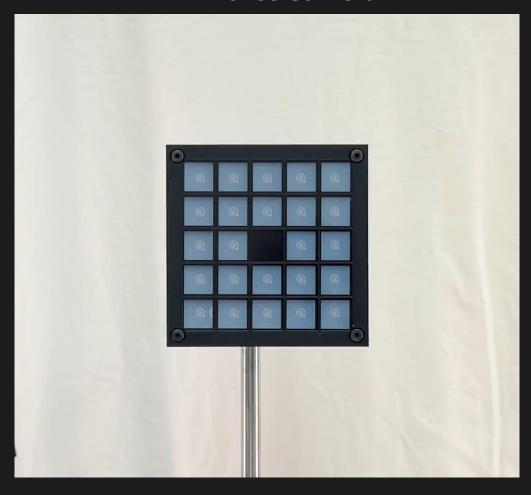


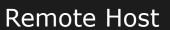


Masks on Transparency

## Self-Powered Minimalist Camera

#### Minimalist Camera





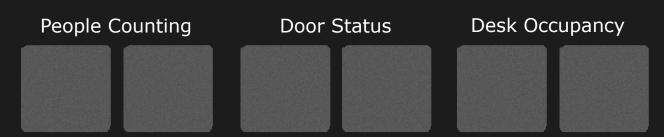


## Workspace Monitoring with 6 Pixels

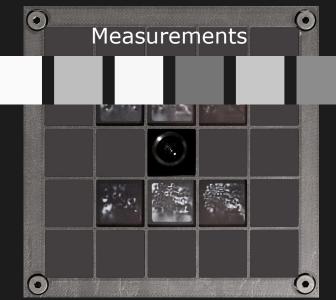
#### Traditional Camera



#### Minimalist Camera

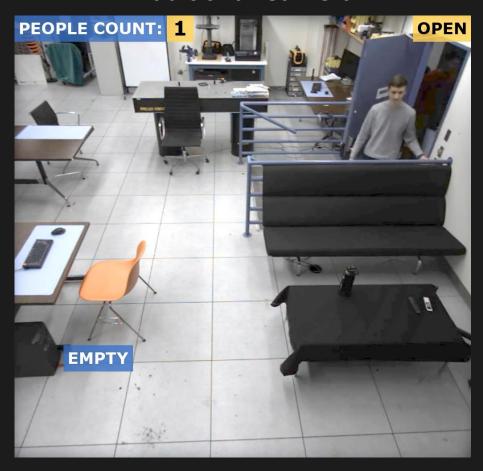


#### Minimalist Camera Prototype



## Workspace Monitoring with 6 Pixels

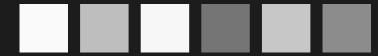
#### Traditional Camera



#### Minimalist Camera

People Counting Door Status Desk Occupancy

Measurements

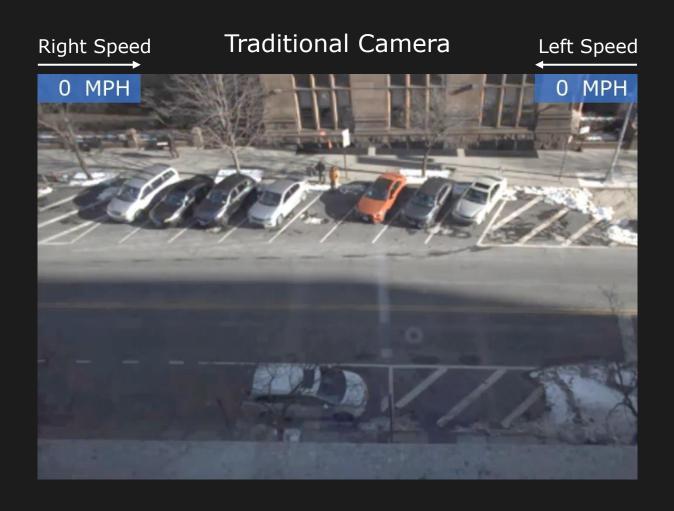


People Count: 1.16 RMS error

Door Status: 95.4%

Desk Occupancy: 99.2%

## Traffic Speed Estimation with 8 Pixels



#### Minimalist Camera

















Right Speed Error (RMS): 2.22 MPH

Left Speed Error (RMS): 2.38 MPH

### Minimalist Vision with Freeform Pixels

Cameras on Infrastructure



Cameras Carried by People



Minimalist Camera



Acknowledgements

Mikhail Fridberg, Carl Vondrick, Behzad Kamgar-Parsi

### Minimalist Vision with Freeform Pixels

Jeremy Klotz and Shree K. Nayar

Columbia University

ECCV 2024

## Why Best Paper

- Minimal information needed to solve a task
  - → Compressing
- Algorithm vs Data
  - > Freeform pixels as new data modality
    - Fast
    - Privacy Protection

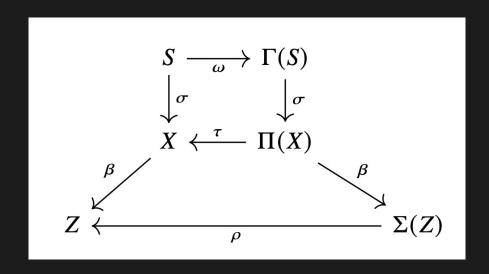
## Freeform Pixels

- Data Modality
  - Structured Data > Location Center
    - RGB
    - Event Camera
    - Point Cloud & Mesh
  - Semantic Data -> Object Center
    - Text
    - Keypoint & Skeleton
    - Freeform Pixels

# Multimodality and Taxonomy

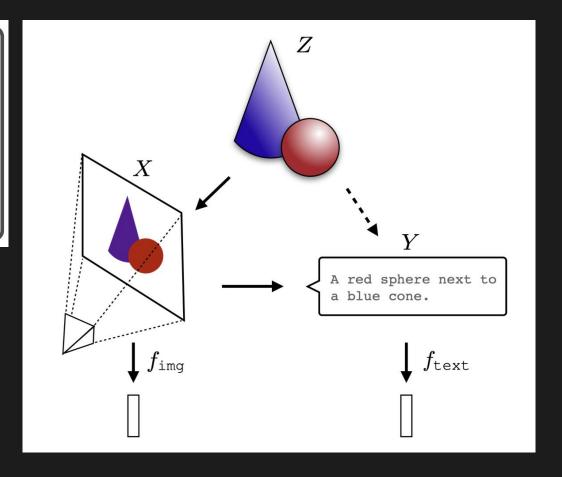


# Multimodality and Taxonomy

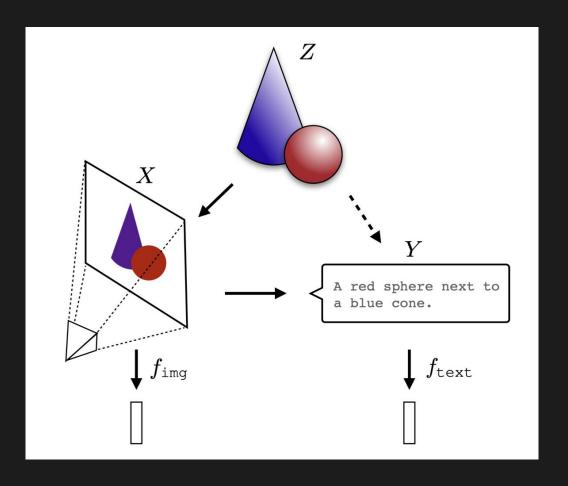


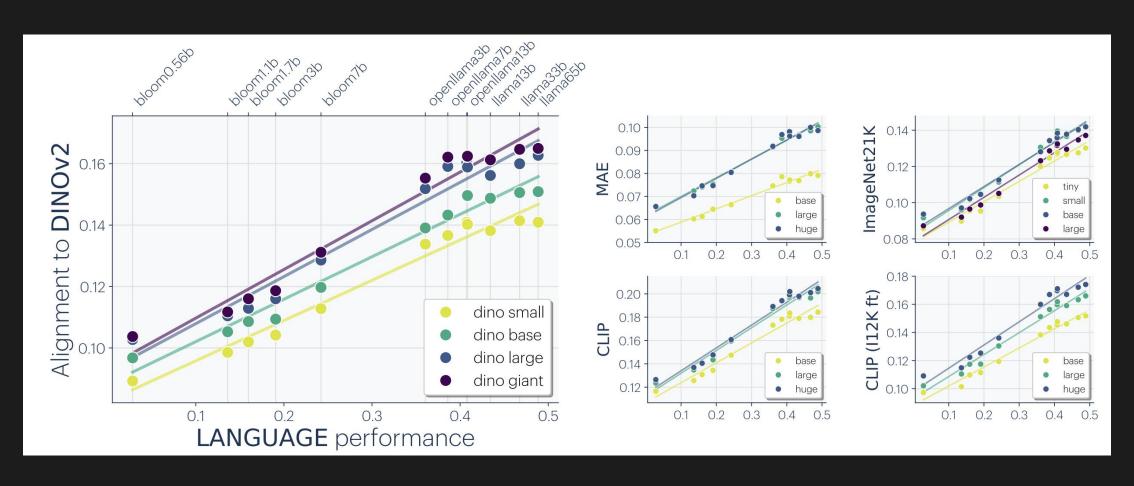
#### **The Platonic Representation Hypothesis**

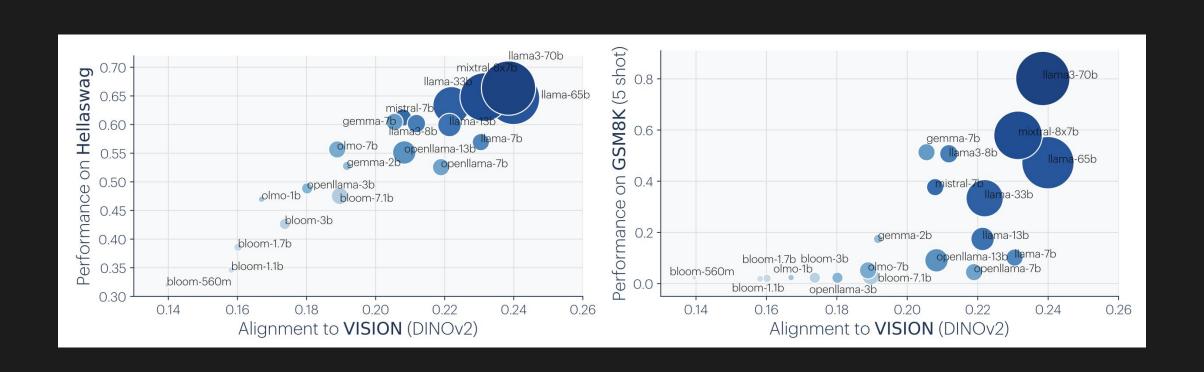
Neural networks, trained with different objectives on different data and modalities, are converging to a shared statistical model of reality in their representation spaces.

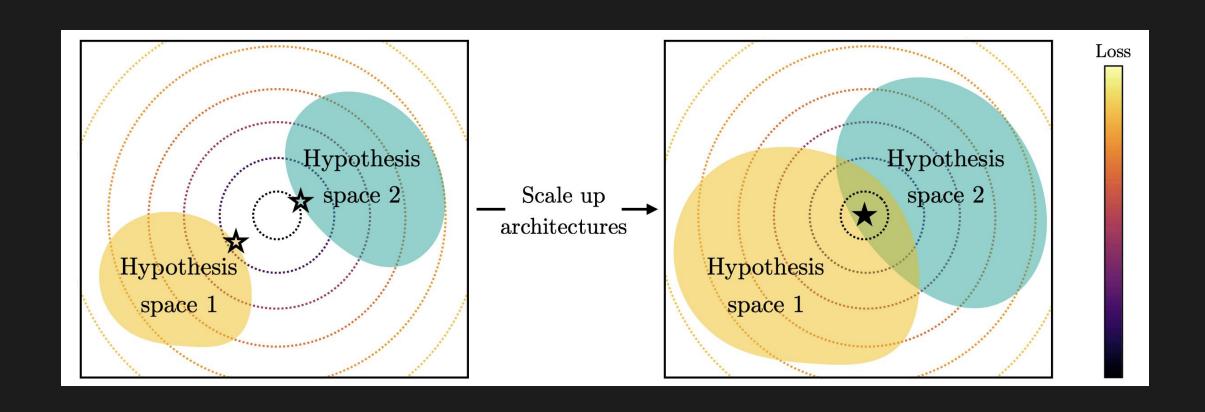


$$K_{\mathrm{img}}(i,j) = \langle f_{\mathrm{img}}(x_i), f_{\mathrm{img}}(x_j) \rangle$$
$$K_{\mathrm{text}}(i,j) = \langle f_{\mathrm{text}}(y_i), f_{\mathrm{text}}(y_j) \rangle.$$



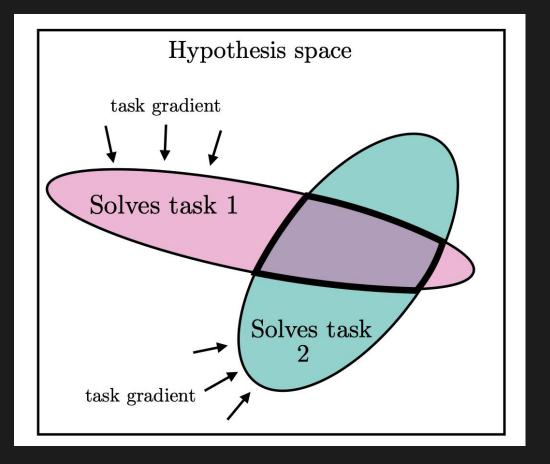






#### The Multitask Scaling Hypothesis

There are fewer representations that are competent for N tasks than there are for M < N tasks. As we train more general models that solve more tasks at once, we should expect fewer possible solutions.



## Limitations and Discussion

- Scene Changes
- Convert to CNN