

Towards Efficient Image Compression Without Autoregressive Models

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STRUCT Group Seminar
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OUTLINE

- Authorship
- Background
- Method
- Experiments
- Conclusion

BACKGROUND: Image Compression



Memory Used:

$768 \times 512 \times 3 \times 8 = 9437184$ bits \approx
1.2MB
(24 bits per pixel)

PNG Format:

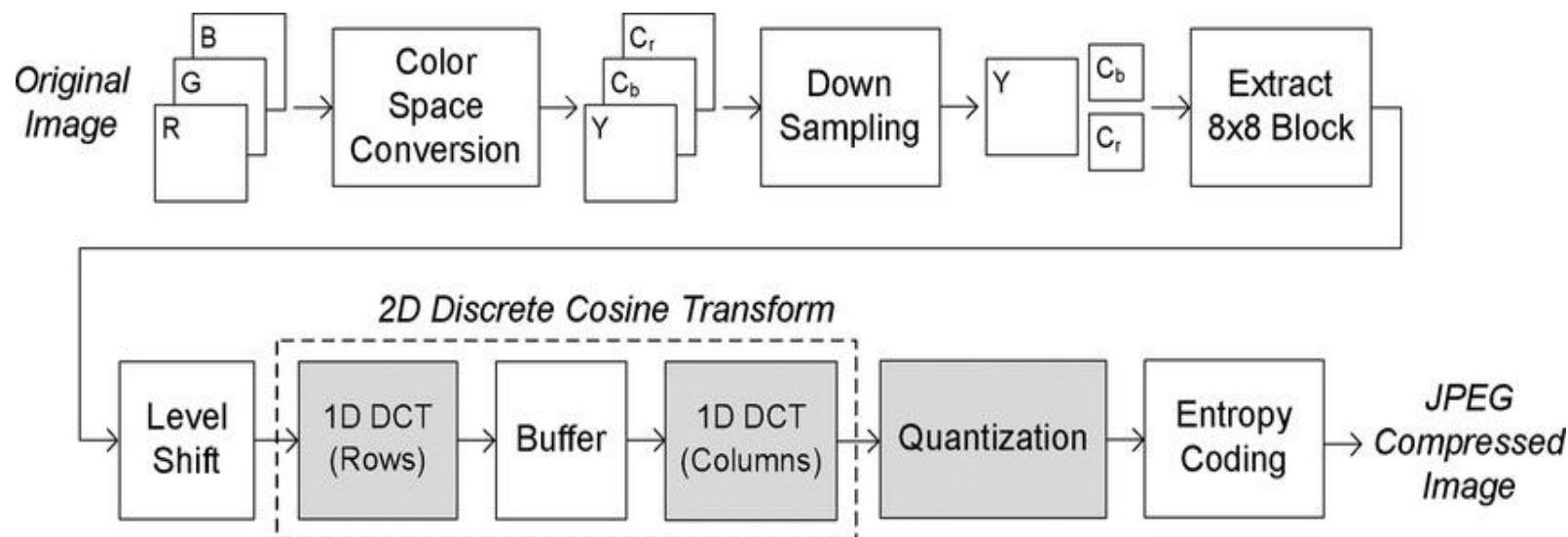
736.5 KB
(15 bits per pixel)

JPEG Format:

34 KB
(0.7 bits per pixel)

BACKGROUND: Conventional Image Compression

- ◆ Transform
- ◆ Quantization
- ◆ Entropy coding



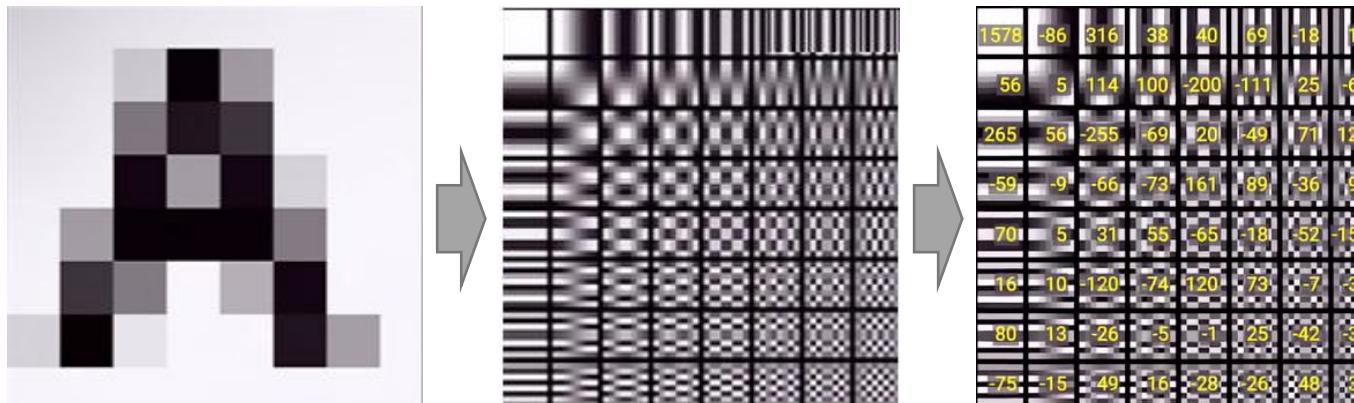
BACKGROUND: Conventional Image Compression

Transform

Transform to a better space

(in JPEG, remove information that eyes are not great at perceiving)

- Color Space Conversion
- Discrete Cosine Transform



$$F(u, v) = \frac{1}{4} C(u)C(v) \left[\sum_{x=0}^7 \sum_{y=0}^7 f(x, y) * \right.$$

$$\left. \cos \frac{(2x+1)u\pi}{16} \cos \frac{(2y+1)v\pi}{16} \right]$$

$$f(x, y) = \frac{1}{4} \left[\sum_{u=0}^7 \sum_{v=0}^7 C(u)C(v) F(u, v) \right.$$

$$\left. \cos \frac{(2x+1)u\pi}{16} \cos \frac{(2y+1)v\pi}{16} \right]$$

where: $C(u), C(v) = 1/\sqrt{2}$ for $u, v = 0$;

$C(u), C(v) = 1$ otherwise.

BACKGROUND: Conventional Image Compression

Quantization

$$F^Q(u,v) = \text{Integer Round} \left(\frac{F(u,v)}{Q(u,v)} \right)$$

560	-41	-57	-12	-4	0	1	1
-180	-25	43	14	12	0	0	-1
42	17	16	-3	-4	-4	-2	0
-1	-12	-11	-3	3	4	4	2
1	2	4	1	-1	-3	-3	-1
1	0	-1	0	5	4	4	2
-2	-3	-1	0	5	4	4	2
2	3	2	0	-3	-4	-4	-2



04	03	04	04	04	06	11	15
03	03	03	04	05	08	14	19
03	04	04	05	08	12	16	20
04	05	06	07	12	14	18	20
06	06	09	11	14	17	21	23
09	12	12	18	23	22	25	21
11	13	15	17	21	23	25	21
13	12	12	13	16	19	21	21

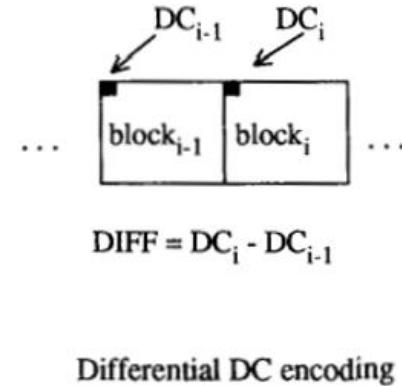
140	-14	-14	-3	1	0	0	0
-60	-8	14	4	2	0	0	0
14	4	4	-1	-1	0	0	0
0	-2	-2	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

$$F^{Q'}(u,v) = F^Q(u,v) * Q(u,v)$$

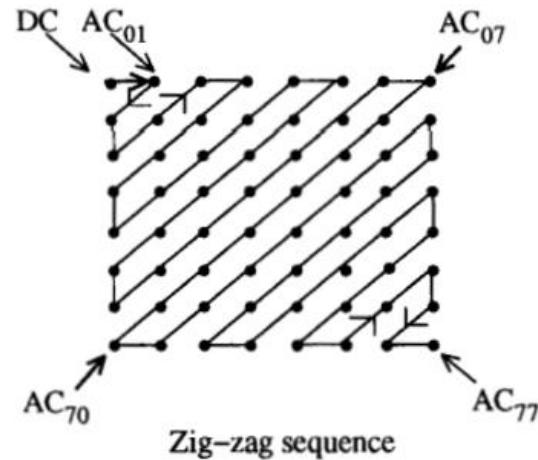
BACKGROUND: Conventional Image Compression

Entropy coding

- ◆ Huffman Coding
- ◆ Arithmetic coding



Differential DC encoding

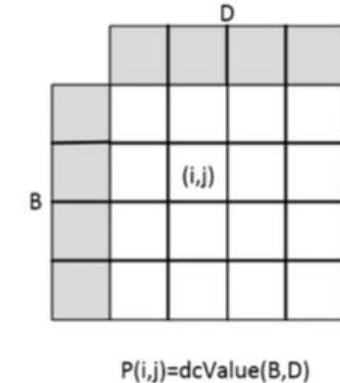
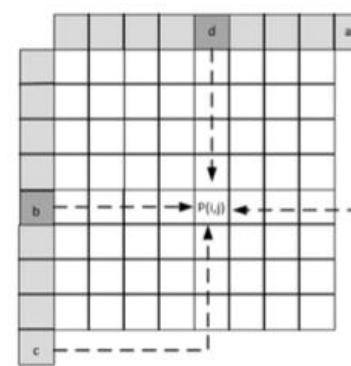


BACKGROUND: Conventional Image Compression

Other tricks

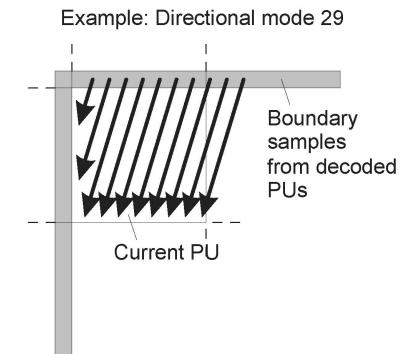
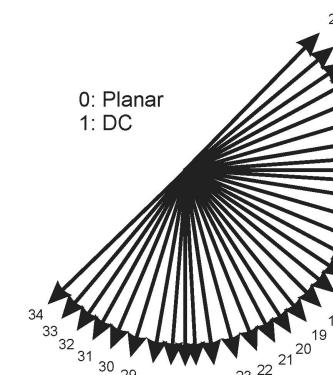
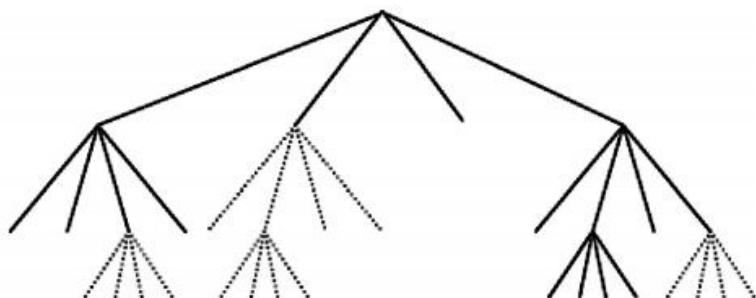
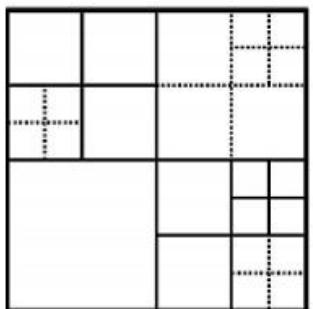
- ◆ Residual Prediction
- ◆ Coding Tree Units
- ◆ Coarse to Fine Prediction

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$$P(i,j) = \text{dcValue}(B, D)$$

Reduce coded content through various predictive strategies



BACKGROUND: E2E Image Compression

- ◆ Transform

Transfer to a latent space

- ◆ Quantization

--> add noise

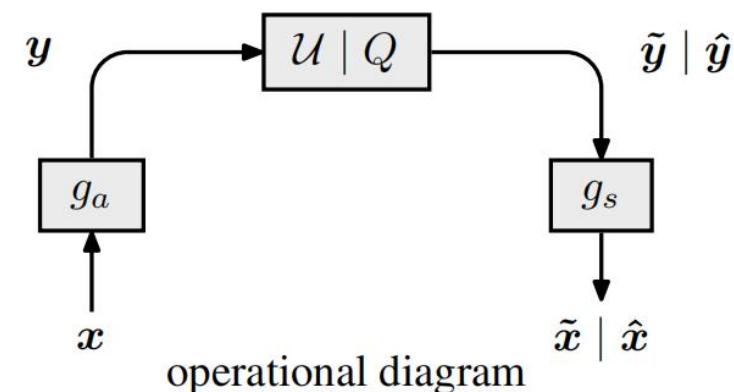
- ◆ Entropy coding

The lower the entropy of the latent variable y , the lower the bitrate

$$R = E_{\hat{y} \sim m}[-\log_2 p_{\hat{y}}(\hat{y})]$$

- ◆ Training Strategy

Trade off between distortion and rate: $L = \lambda \cdot D + R$

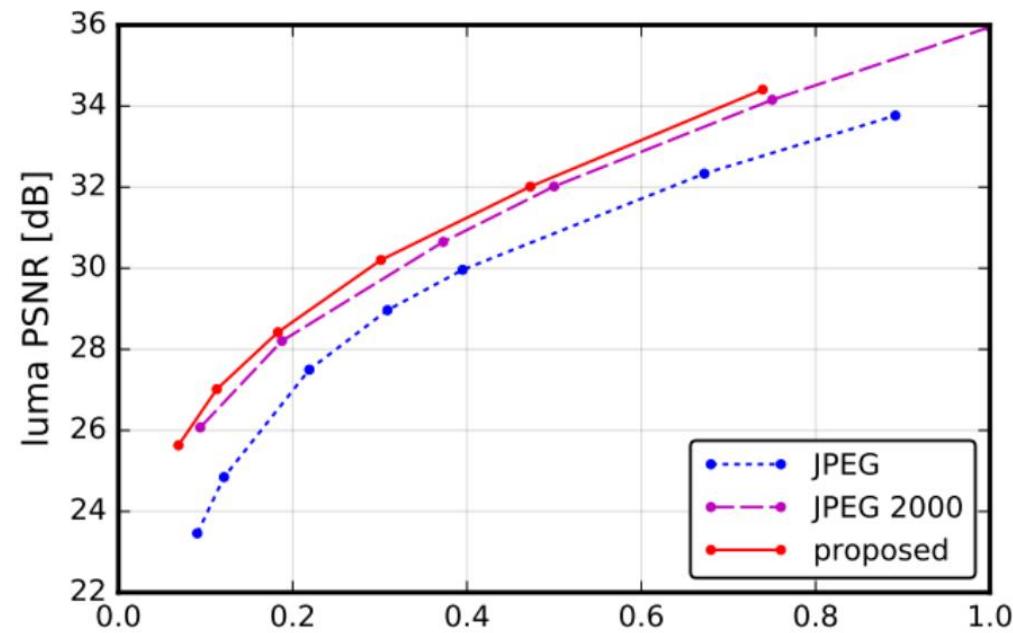
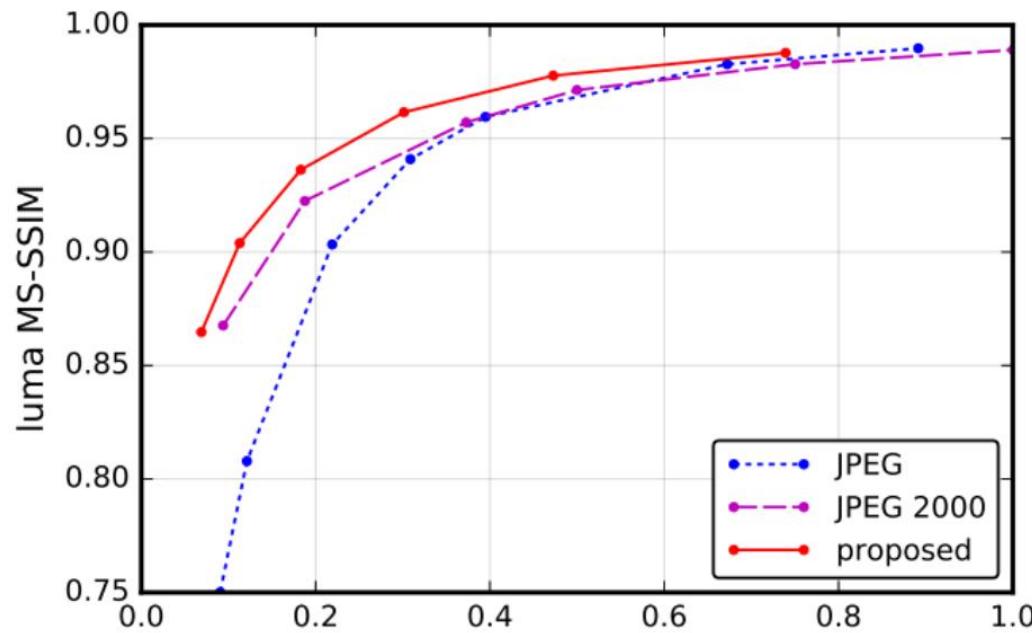


BACKGROUND: E2E Image Compression

◆ Metrics

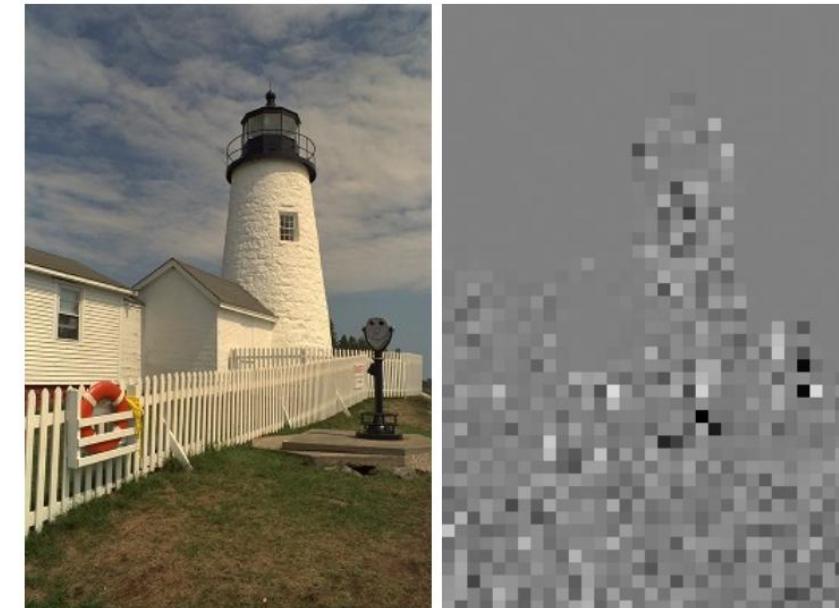
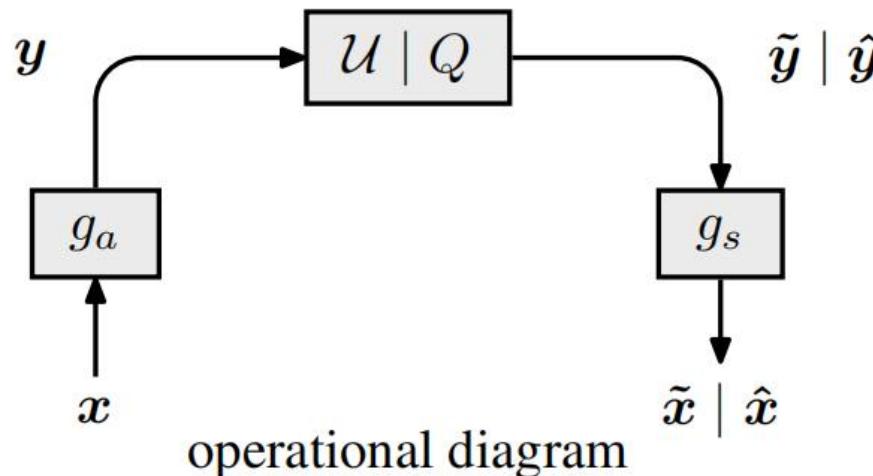
RD-Curve

BD-rate



BACKGROUND: E2E Image Compression

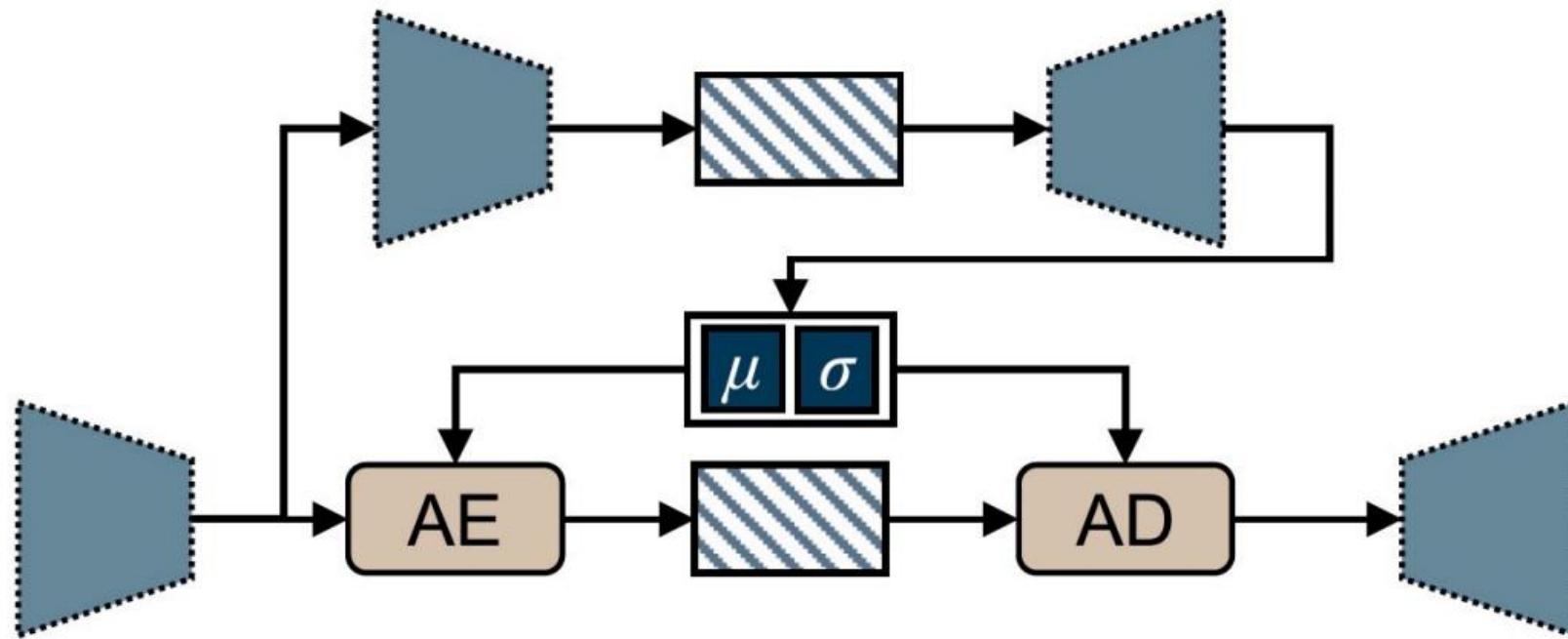
- ◆ Visualize a subset of the y
 - Ideal state: No spatial coupling
 - Actually: Non-zero responses are highly clustered in areas of high contrast



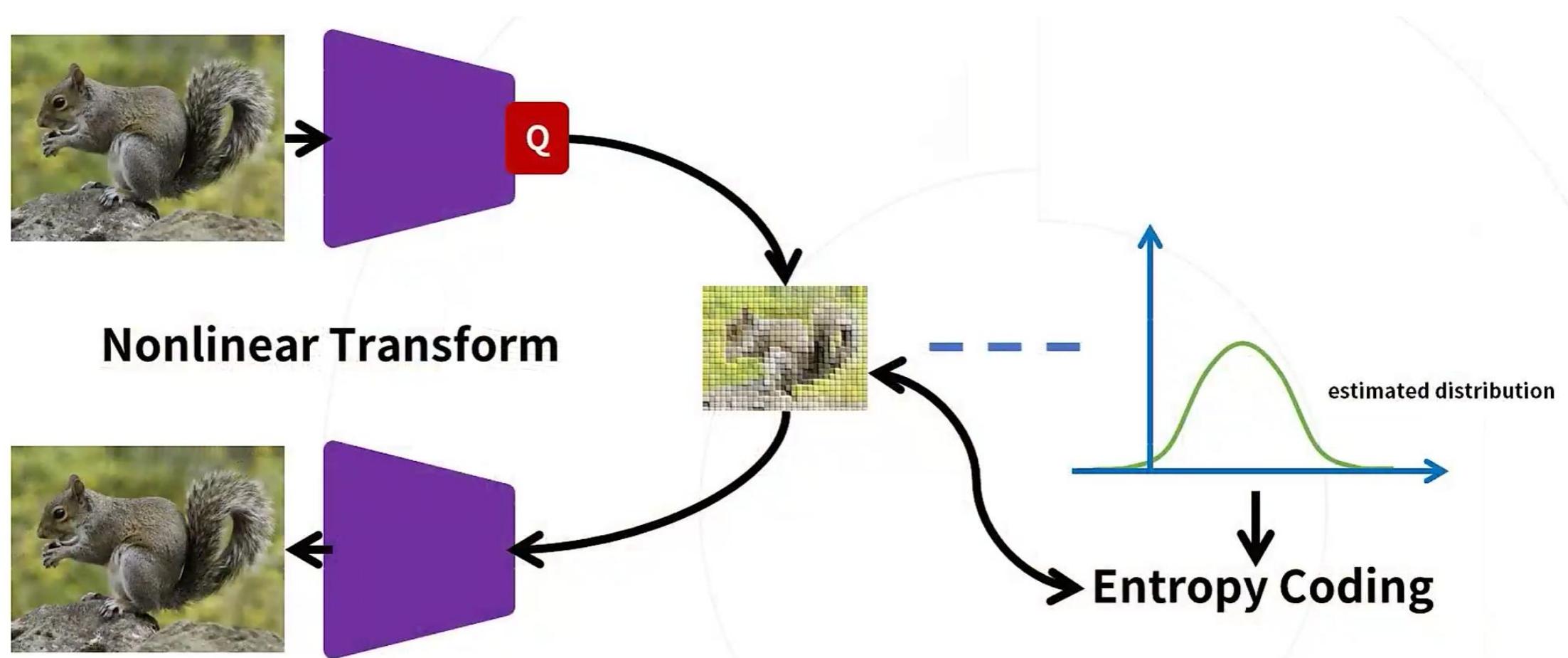
BACKGROUND: E2E Image Compression

Introducing a hyperprior

- When the entropy distribution is consistent with the real distribution, the stream is minimum
- Simplified the distribution of each pixel to a Gaussian distribution
- Predict μ and σ for each pixel use hyperprior

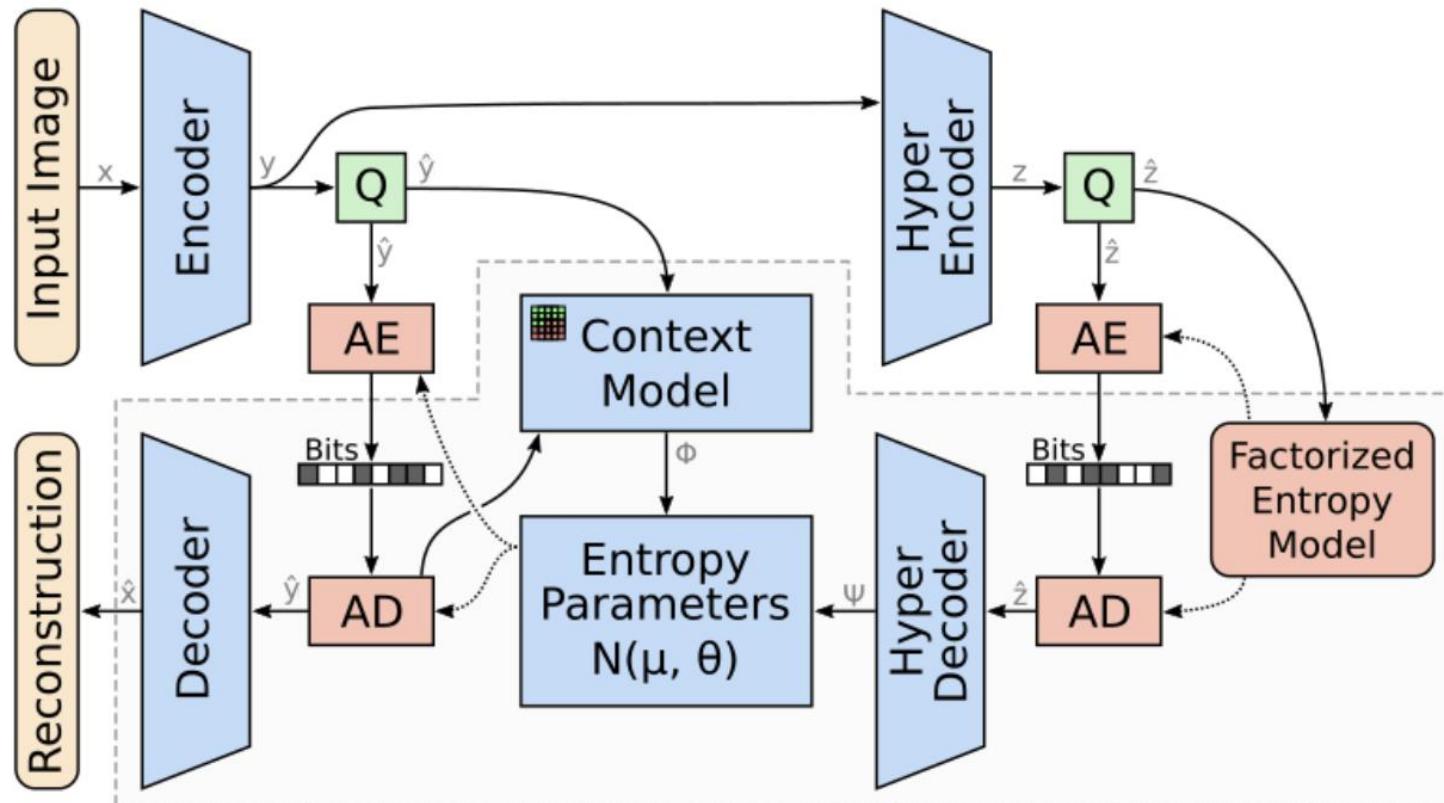


BACKGROUND: E2E Image Compression



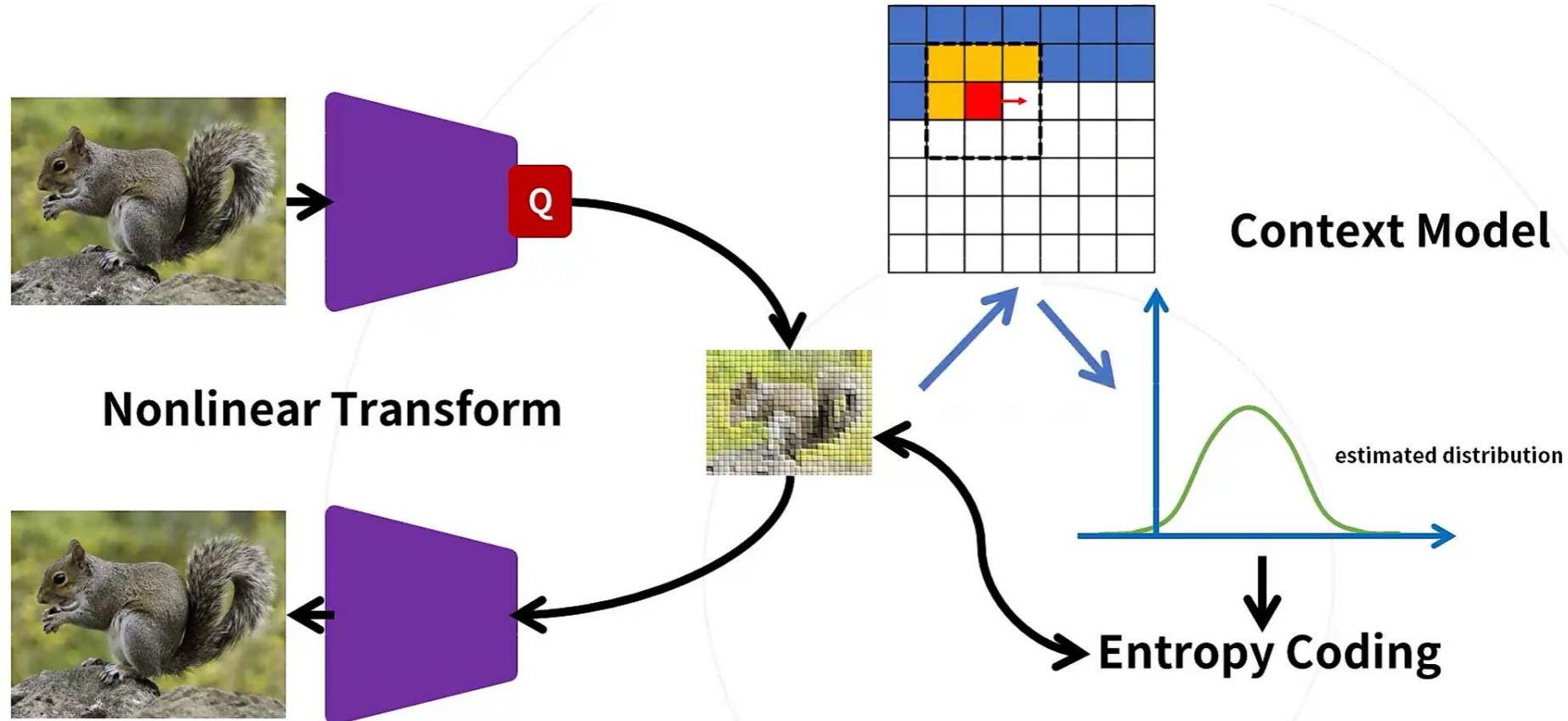
BACKGROUND: E2E Image Compression

Introducing autoregressive



BACKGROUND: E2E Image Compression

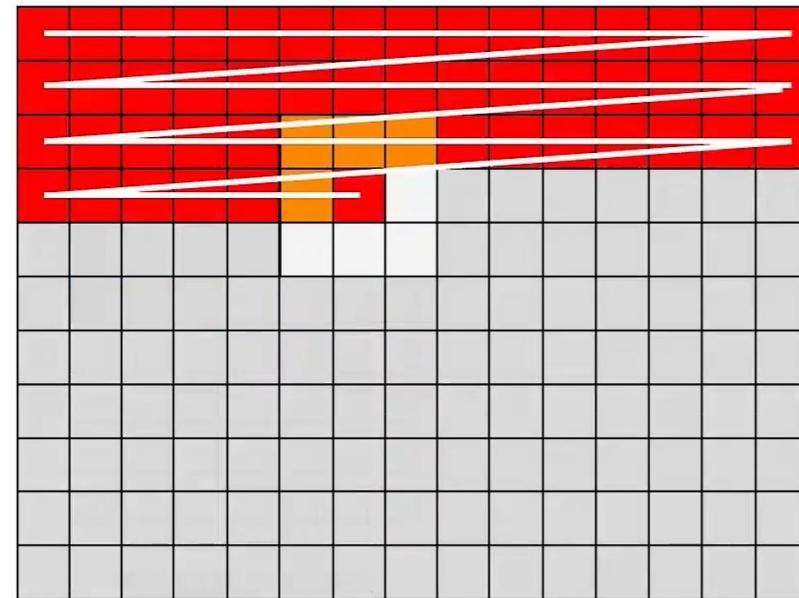
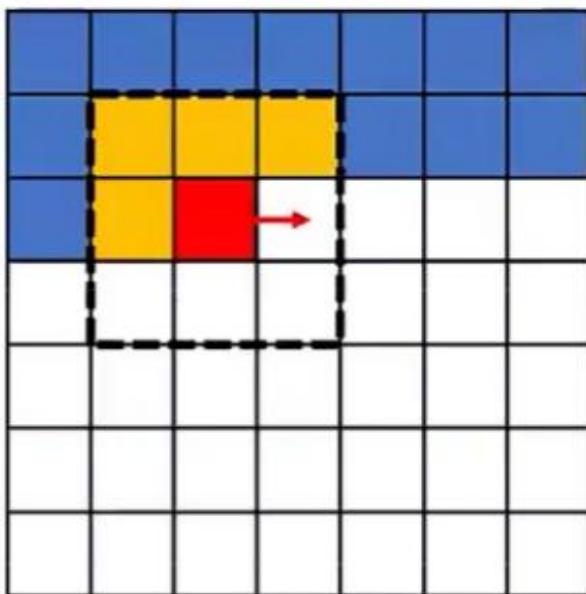
Introducing autoregressive



BACKGROUND: E2E Image Compression

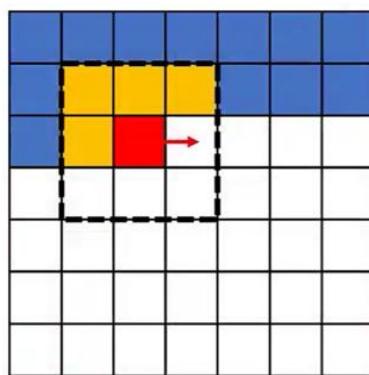
Introducing autoregressive

- ◆ More spatial context information
- ◆ No additional bitstream
- ◆ Serial coding, high time complexity $O(HW)$

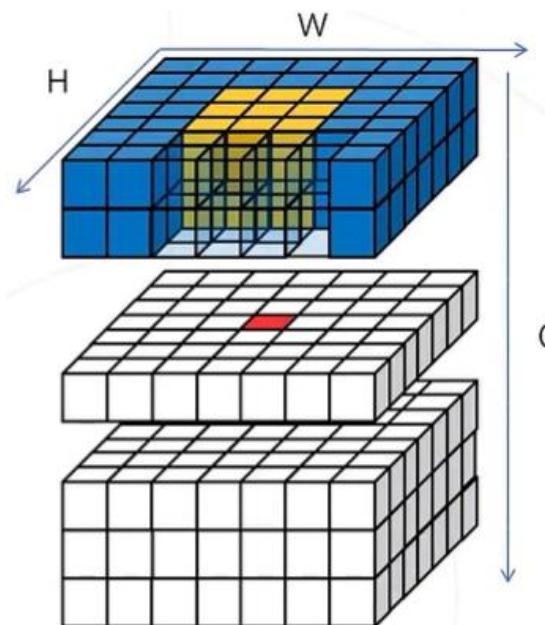


BACKGROUND: E2E Image Compression

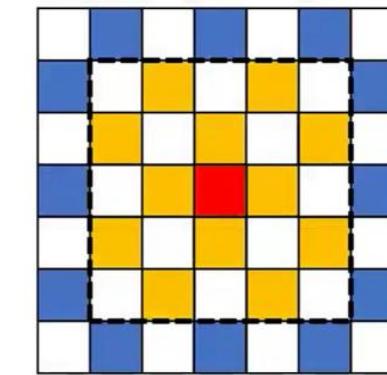
Autoregressive acceleration



Autoregressive
Minnen et al., (2018)



Channel-wise
Minnen et al., (2020)

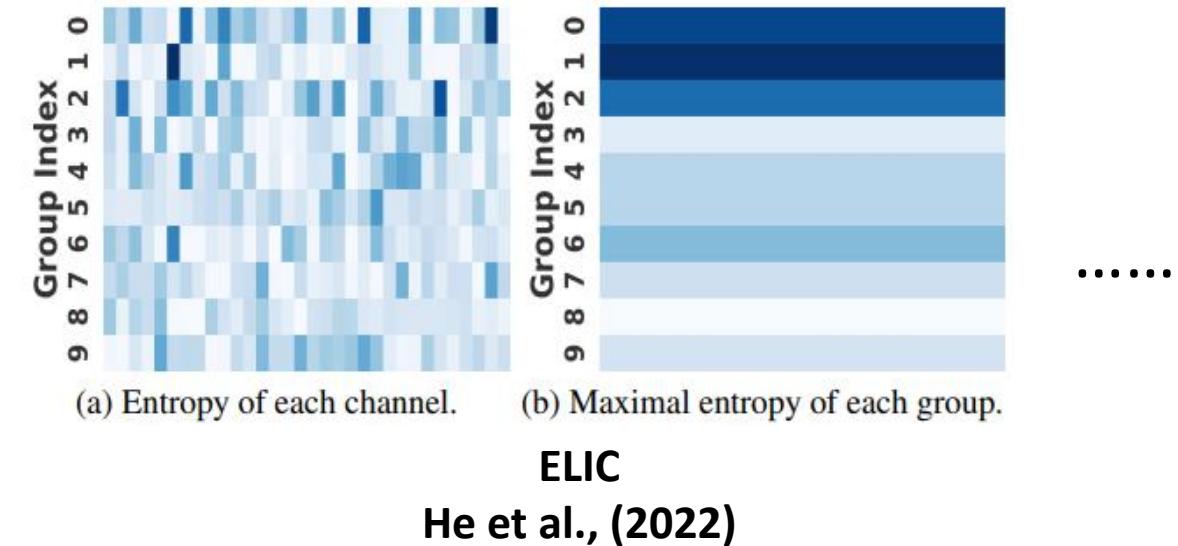
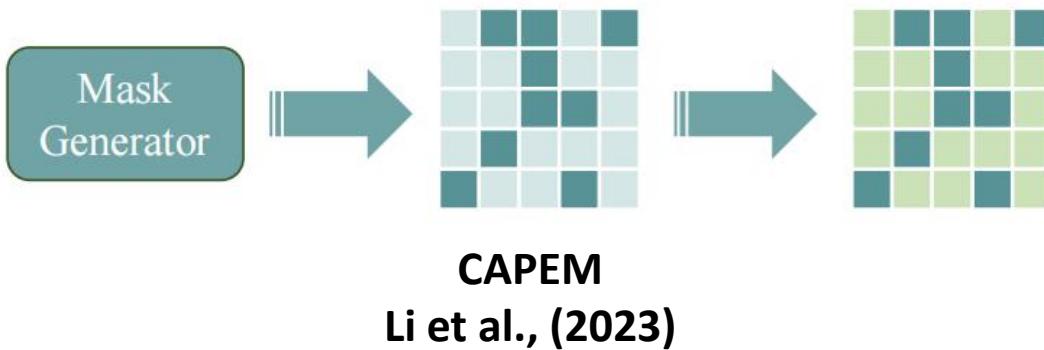


Checkerboard
He et al., (2021)

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BACKGROUND: E2E Image Compression

Autoregressive acceleration



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METHOD: Motivation

- ◆ Why do we use autoregressive models?

Spatial location independence of elements

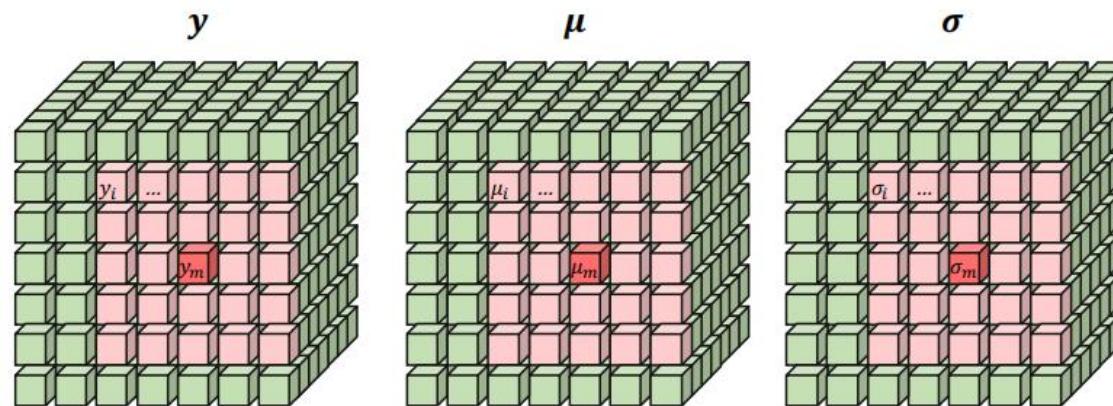
- ◆ Basic idea

Use correlation loss to reduce the spatial correlation

METHOD: Correlation Loss

- ◆ Calculate the correlation of each point

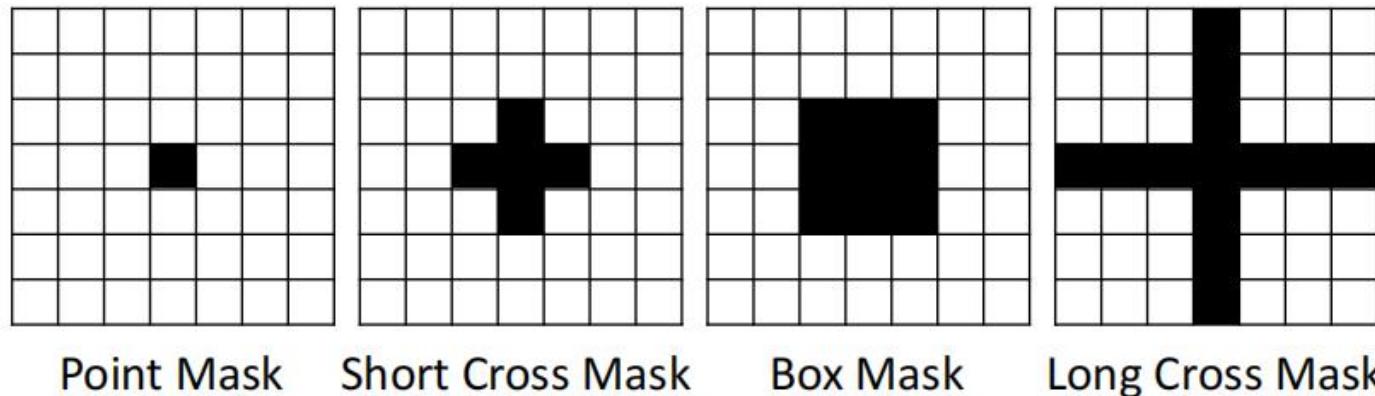
$$Corr_Map_{k \times k}[i] = \mathbb{E}_{x \sim p(x)} \left[\left(\frac{y_i - \mu_i}{\sigma_i} \right) \left(\frac{y_m - \mu_m}{\sigma_m} \right) \right], 0 \leq i < k^2$$



METHOD: Correlation Loss

- ◆ Apply masks to limit autocorrelation

$$Masked_Map_{k \times k}[i] = Corr_Map_{k \times k}[i] \odot Mask$$



- ◆ Calculate L2Loss as correlation loss

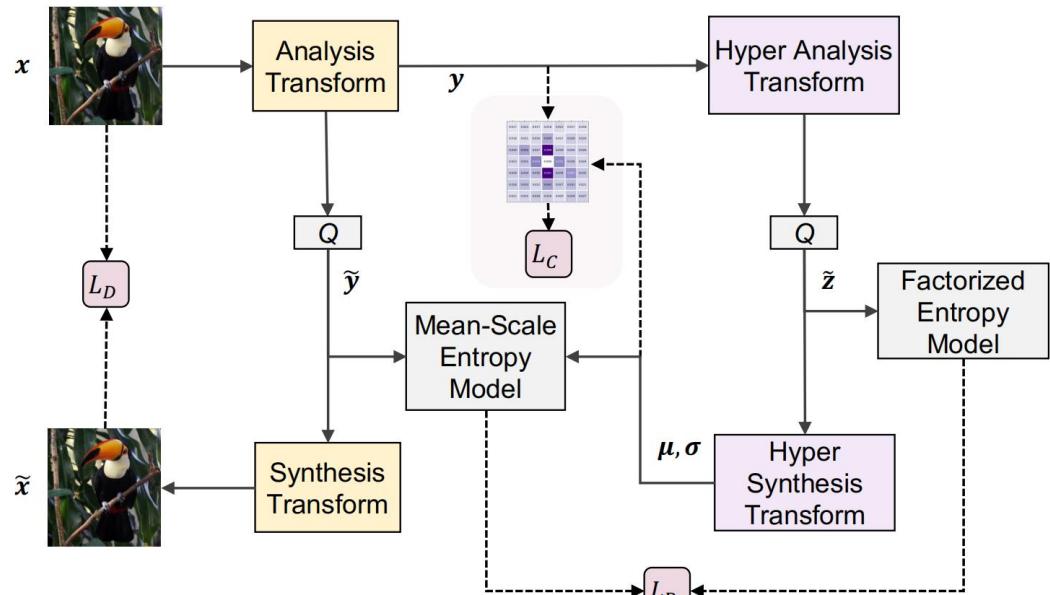
$$L_{corr} = \|Masked_Map_{k \times k}[i]\|^2$$

METHOD: Correlation Loss

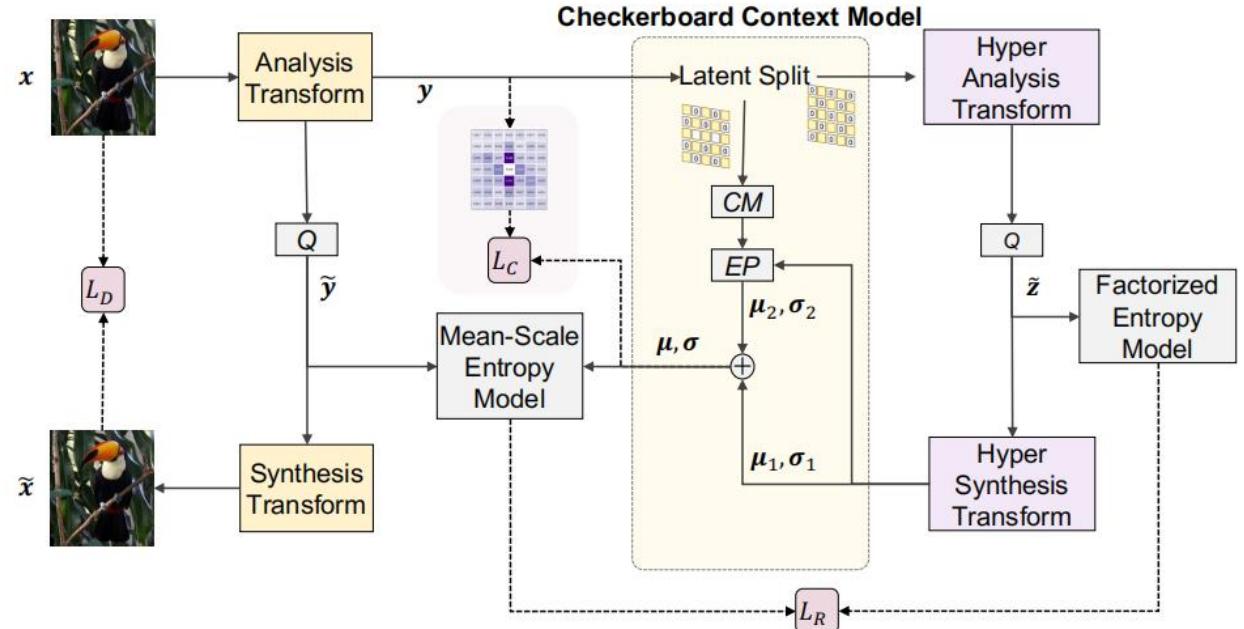
◆ Loss Function

$$RD_{loss} = E_{x \sim p(x)} \left[-\log_2 p_{\hat{y}|\hat{z}}(\hat{y} \mid \hat{z}) - \log_2 p_{\hat{z}}(\hat{z}) \right] + \lambda \cdot E_{x \sim p(x)} [d(x, \hat{x})] + \alpha \cdot [L_{corr}]$$

METHOD: Structure



Combine Hyperprior



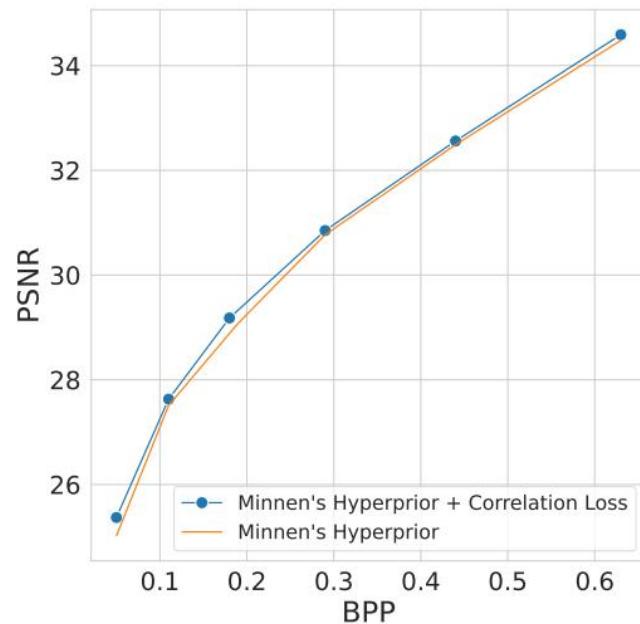
Combine Checkerboard

OUTLINE

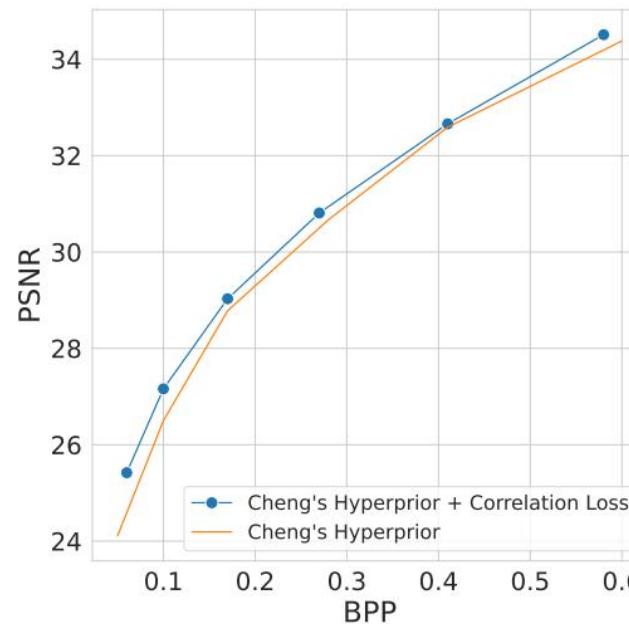
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EXPERIMENTS: RD-Performance

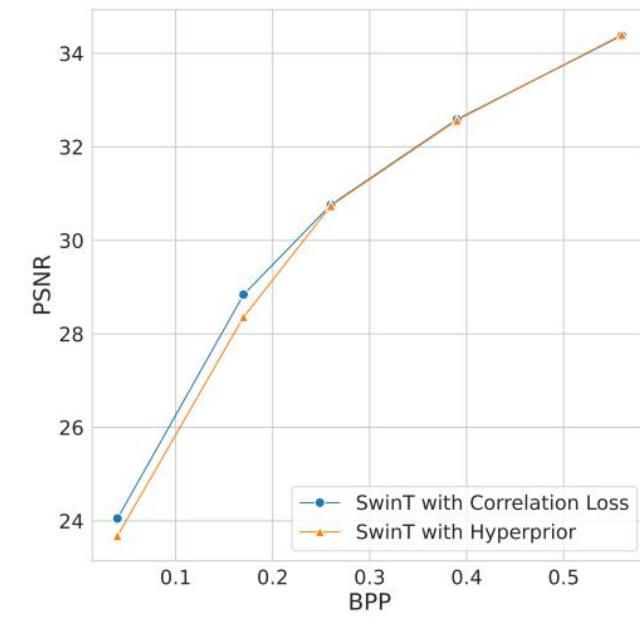
Combine with baseline methods



(a) Minnen's mean scale hyperprior



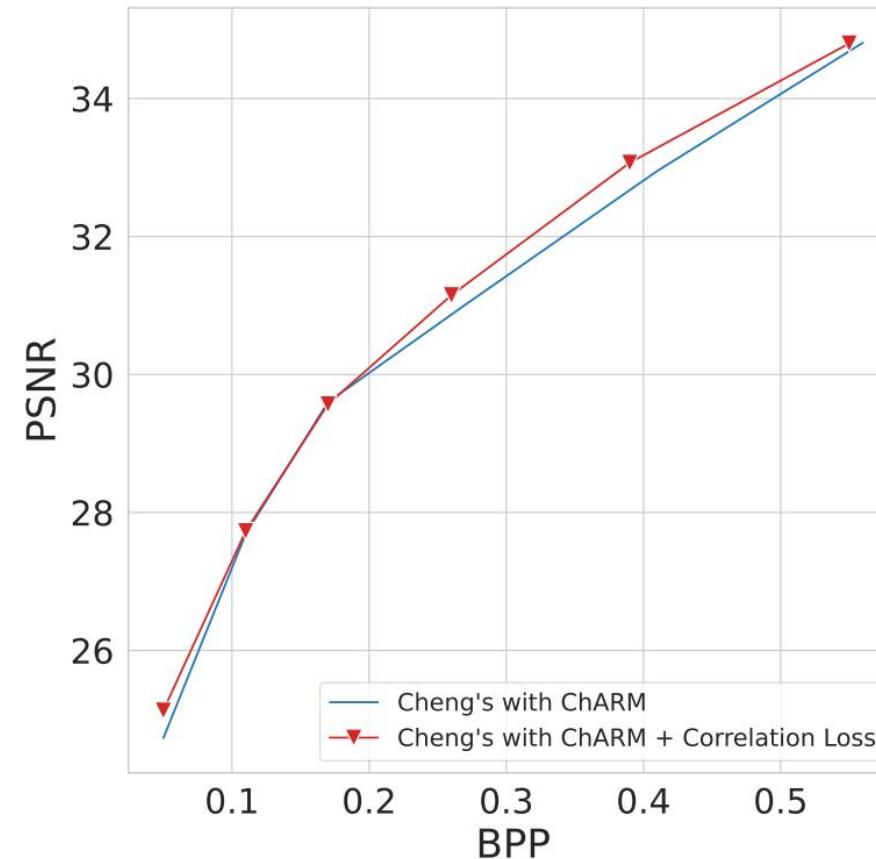
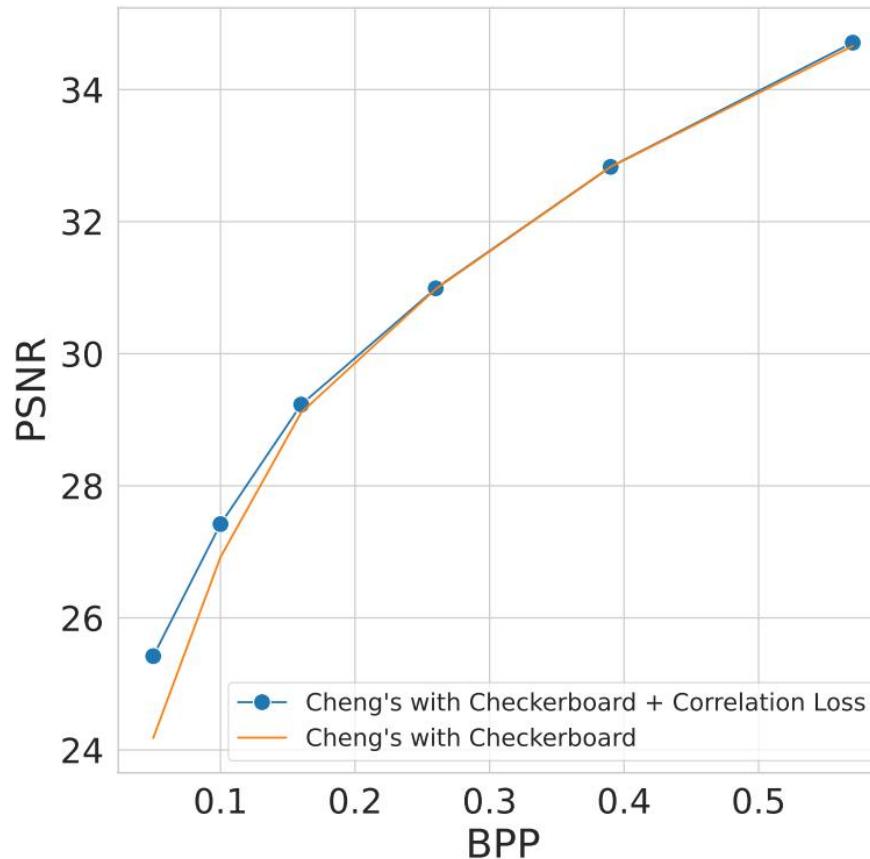
(b) Cheng's mean scale hyperprior



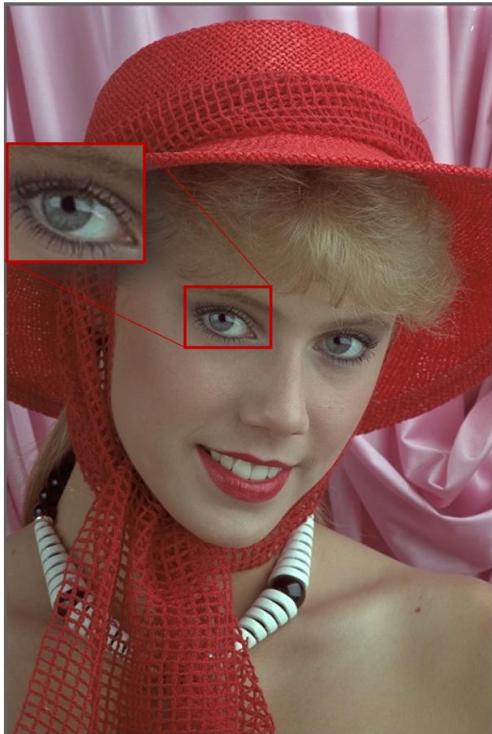
(c) SwinT mean scale hyperprior

EXPERIMENTS: RD-Performance

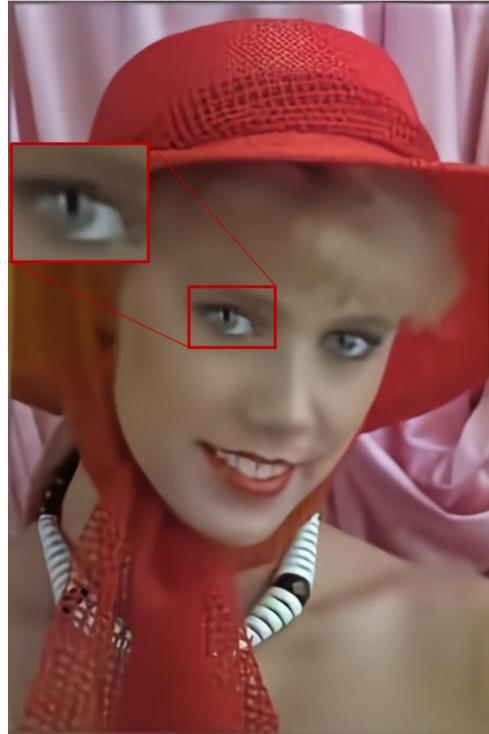
Combine with autoregressive models



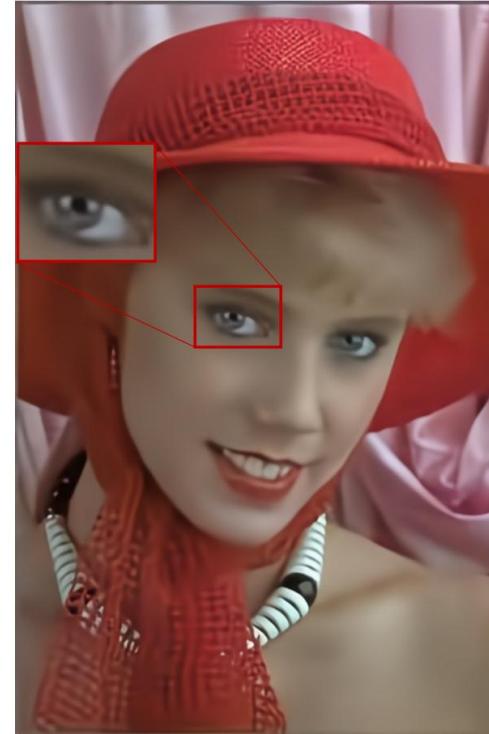
EXPERIMENTS: Reconstructed image quality



Original Image

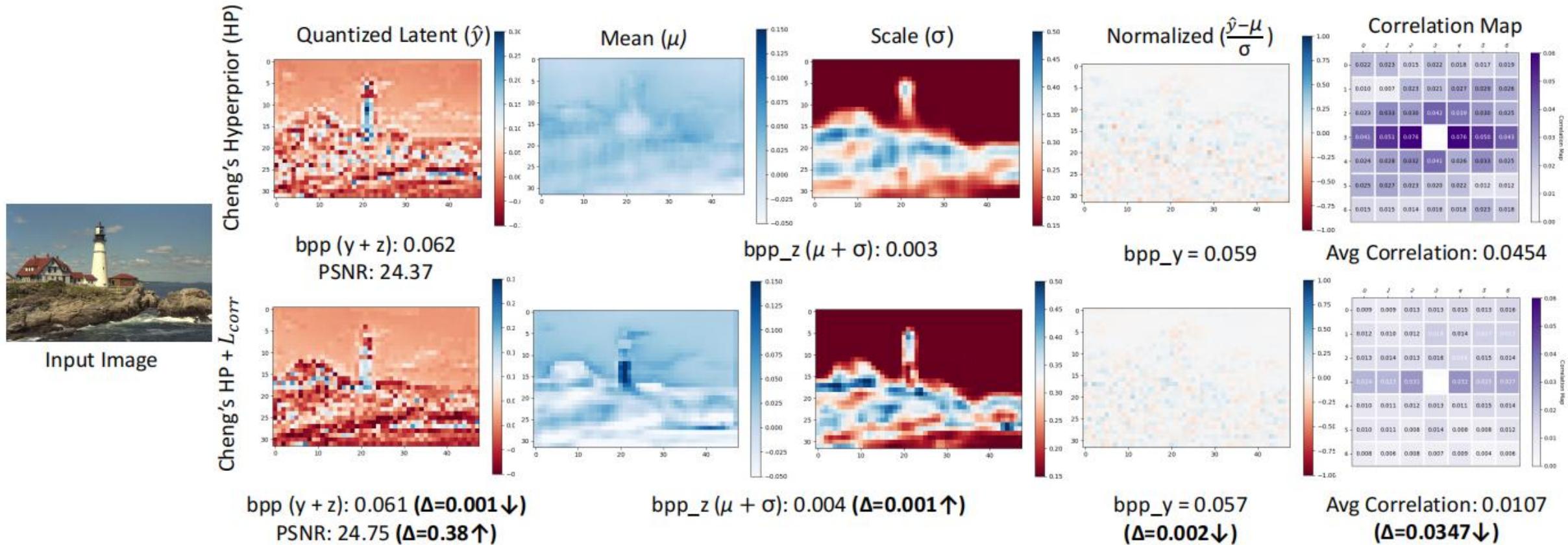


Cheng's with Hyperprior
BPP: 0.06, PSNR: 27.74dB



Cheng's with Correlation loss
BPP: 0.06, PSNR: 28.36dB

EXPERIMENTS: Visualization

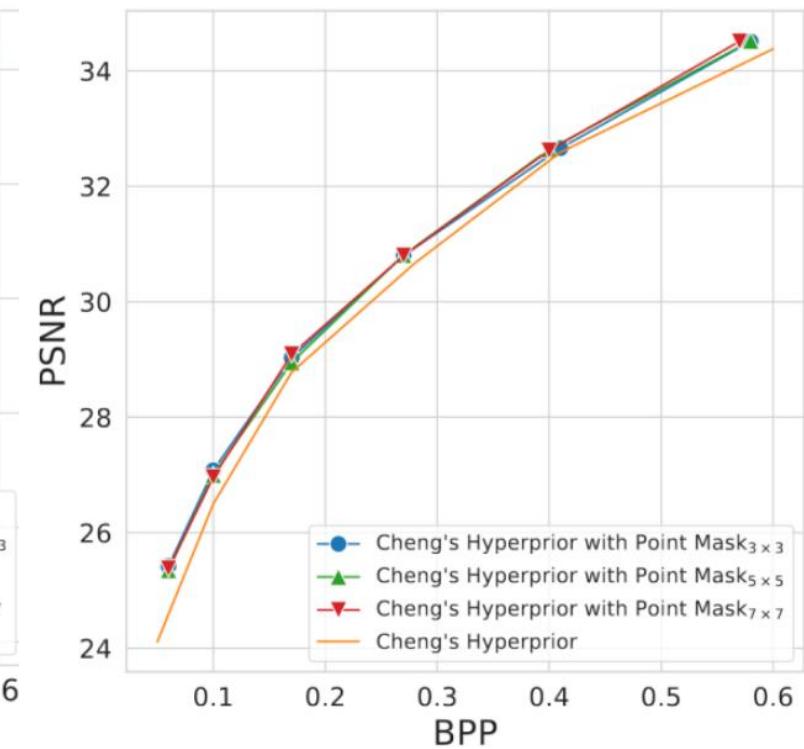
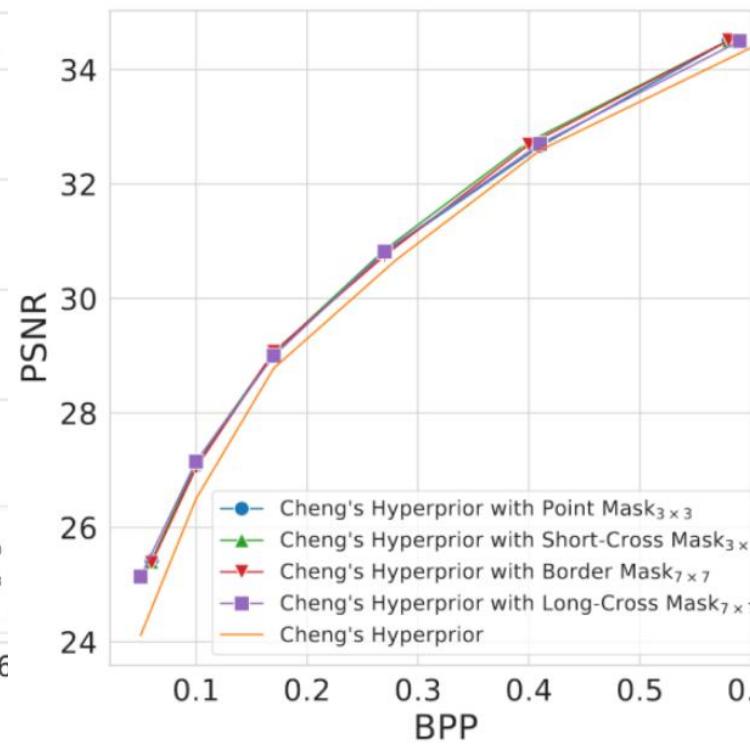
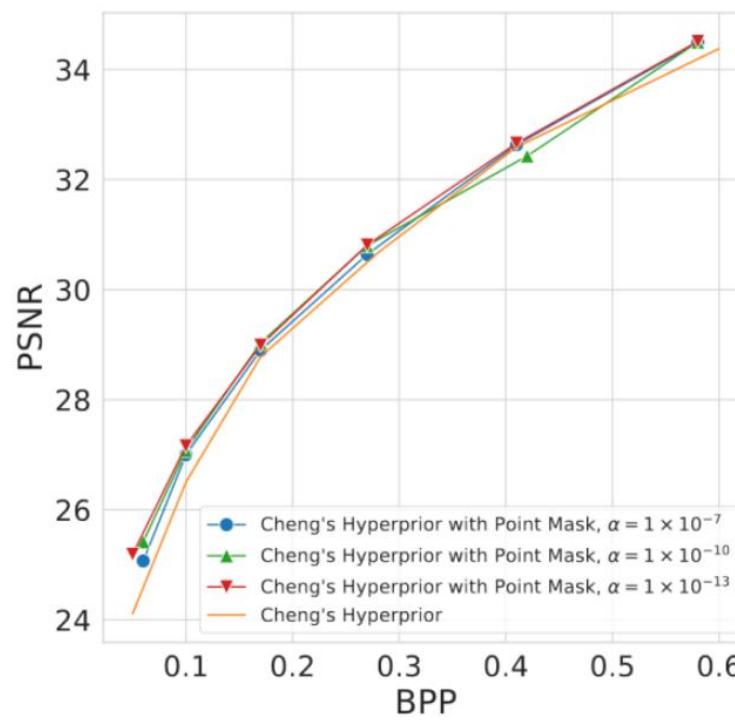


EXPERIMENTS: Complexity tradeoff

Architecture	BD Rate Gains (%)	Inference Time (sec)
Cheng's Hyperprior (CH)	—	4.66
CH + Correlation Loss (Proposed)	9.5	4.66
CH + Checkerboard	10.37	5.33
CH + Checkerboard + Correlation Loss (Proposed)	16.50	5.33
CH + ChARM	14.69	8.14
CH + ChARM + Correlation Loss (Proposed)	17.99	8.14
CH + AR Context	18.47	251.65

EXPERIMENTS: Ablation study

- ◆ Different α
- ◆ Different mask
- ◆ Different windows



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CONCLUSION

- ◆ Design a loss function to narrow the difference between the predicted distribution and real distribution
- ◆ Improves the performance of existing methods without loss

Thanks for listening!